

Accelerating Linear Systems Solution by Exploiting Low-Rank Approximations to Factorization Error

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IMA Conference on Numerical Linear Algebra and Optimization,
Birmingham, 27-29 June 2018

Objective

- Compute solution to linear system $Ax = b$
- $A \in \mathbb{R}^{n \times n}$ is **ill conditioned**

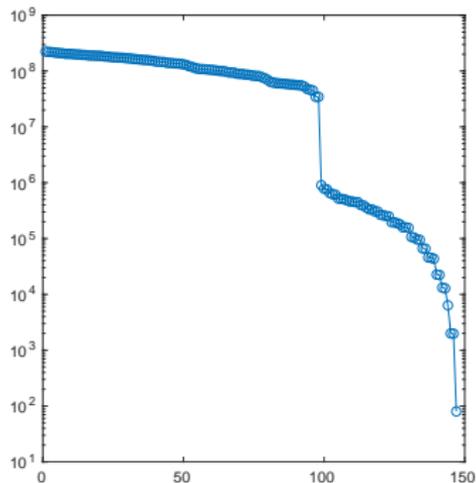
LU-based preconditioner

1. Compute approximate factorization $A = \hat{L}\hat{U} + \Delta A$
 - Half-precision factorization
 - Incomplete LU factorization
 - Structured matrix factorization: Block Low-Rank, \mathcal{H} , HSS,...
2. Solve $\Pi_{LU}Ax = \Pi_{LU}b$ with $\Pi_{LU} = \hat{U}^{-1}\hat{L}^{-1}$ via some iterative method

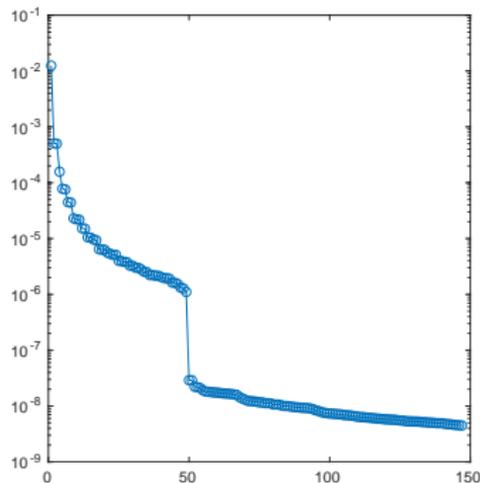
- Convergence to solution may be slow or fail

⇒ **Objective: accelerate convergence**

Matrix lund_a ($n = 147$, $\kappa(A) = 2.8e+06$)



SVD of A



SVD of A^{-1}

- Often, A is ill conditioned due to a **small number of small singular values**
- Then, A^{-1} is **numerically low-rank**

Factorization error might be low-rank?

$$\begin{aligned}\text{Let the error } E &= \hat{U}^{-1}\hat{L}^{-1}A - I = \hat{U}^{-1}\hat{L}^{-1}(\hat{L}\hat{U} + \Delta A) - I \\ &= \hat{U}^{-1}\hat{L}^{-1}\Delta A \approx A^{-1}\Delta A\end{aligned}$$

Does E retain the low-rank property of A^{-1} ?

A novel preconditioner

Consider the preconditioner

$$\Pi_{E_k} = (I + E_k)^{-1}\Pi_{LU}$$

with E_k a rank- k approximation to E .

- If $E = E_k$, $\Pi_{E_k} = A^{-1}$
- If $E \approx E_k$ for some small k , Π_{E_k} can be **computed cheaply**

Preprint

 N. J. Higham and T. Mary, *A New Preconditioner that Exploits Low-Rank Approximations to Factorization Error*, MIMS EPrint 2018.10.

Low-rank gap

$$\varepsilon_k(A) = \min_{W_k} \left\{ \frac{\|A - W_k\|}{\|A\|} : \text{rank}(W_k) \leq k \right\}$$

Eckart-Young-Mirsky

$$\varepsilon_k(A) = \frac{\sigma_{k+1}(A)}{\sigma_1(A)}$$

Problem statement

Quantify **worst-case reduction of the low-rank gap** from A^{-1} to $E = \hat{U}^{-1}\hat{L}^{-1}\Delta A$, i.e find some β such that

$$\varepsilon_k(E) \leq \beta \varepsilon_k(A^{-1})$$

Theorem

$$\varepsilon_k(E) \leq \beta_1 \beta_2 \varepsilon_k(A^{-1})$$

with

$$\varepsilon_k(\hat{U}^{-1}\hat{L}^{-1}) \leq \beta_1 \varepsilon_k(A^{-1})$$

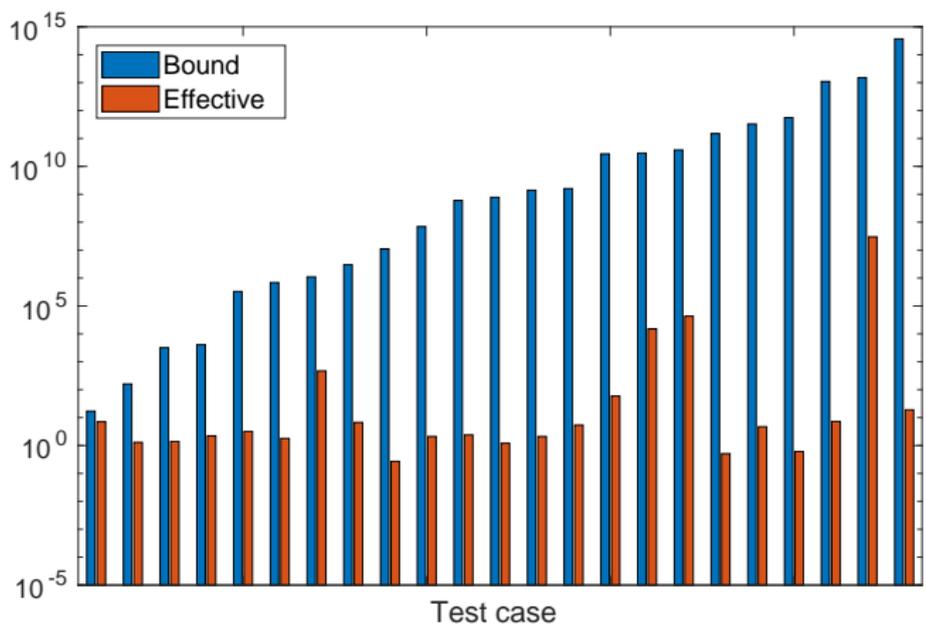
$$\beta_1 = (1 + \|A^{-1}\Delta A\|) \left(1 + \|\hat{U}^{-1}\hat{L}^{-1}\Delta A\|\right)$$

$$\varepsilon_k(E) = \varepsilon_k(\hat{U}^{-1}\hat{L}^{-1}\Delta A) \leq \beta_2 \varepsilon_k(\hat{U}^{-1}\hat{L}^{-1})$$

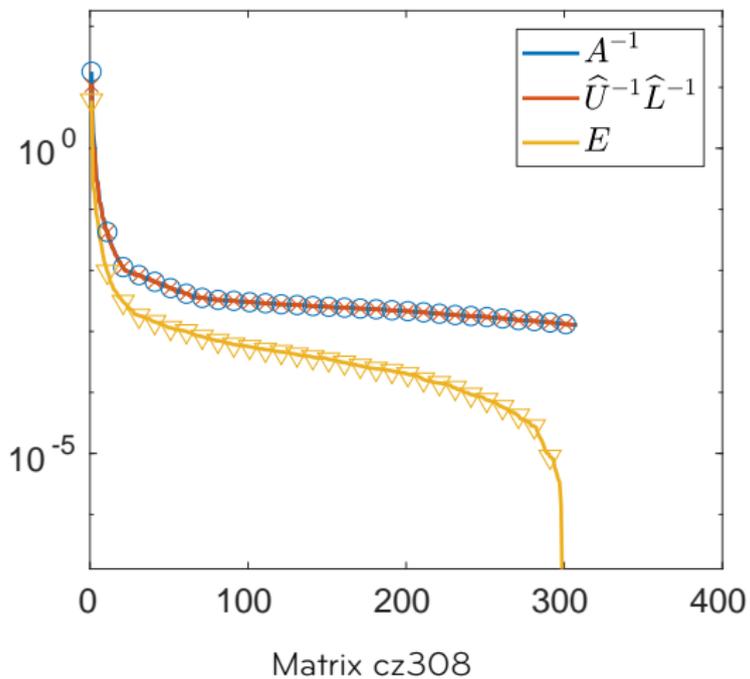
$$\beta_2 = \frac{\|\hat{U}^{-1}\hat{L}^{-1}\| \|\Delta A\|}{\|\hat{U}^{-1}\hat{L}^{-1}\Delta A\|}$$

- β_1 : maximal deviation of the sing. vals. by **additive perturbation**
- β_2 : should be small for **typical ΔA**

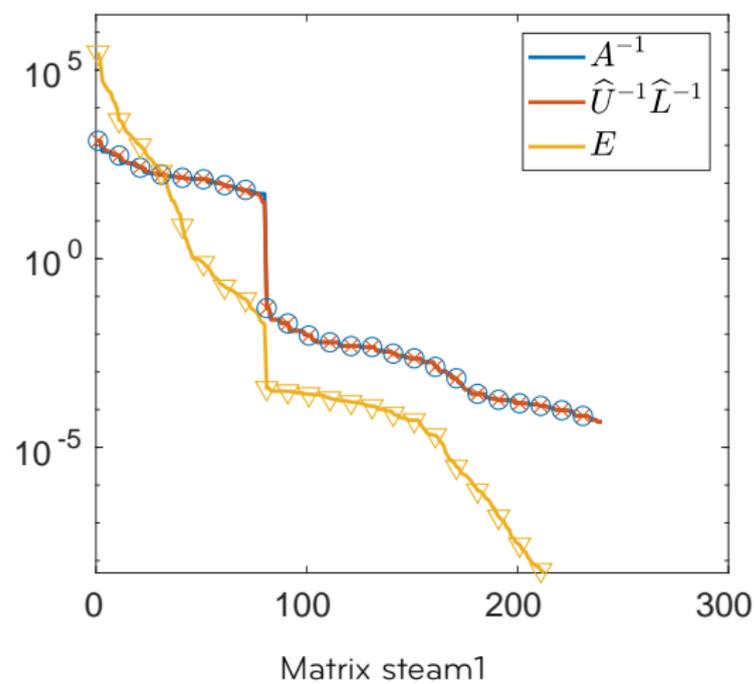
The bound is pessimistic



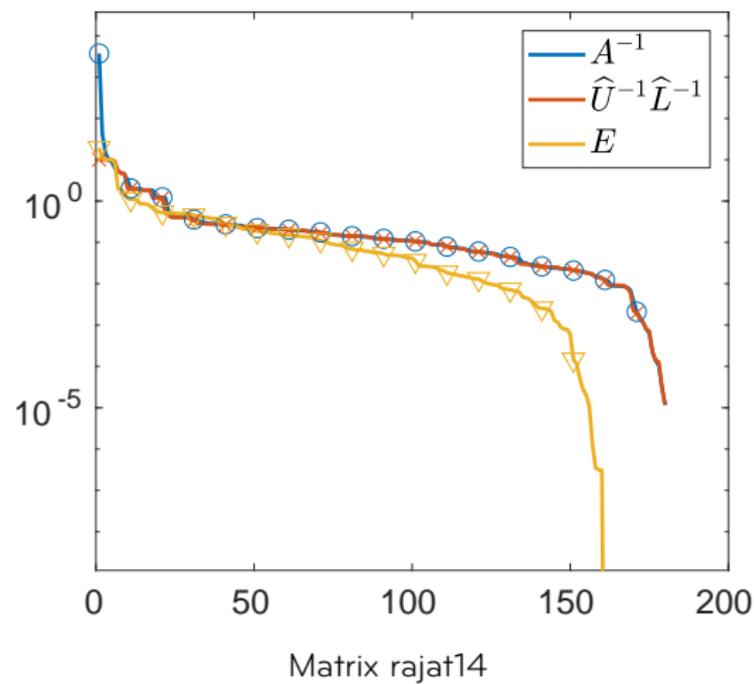
Typical SV distributions of A^{-1} and E



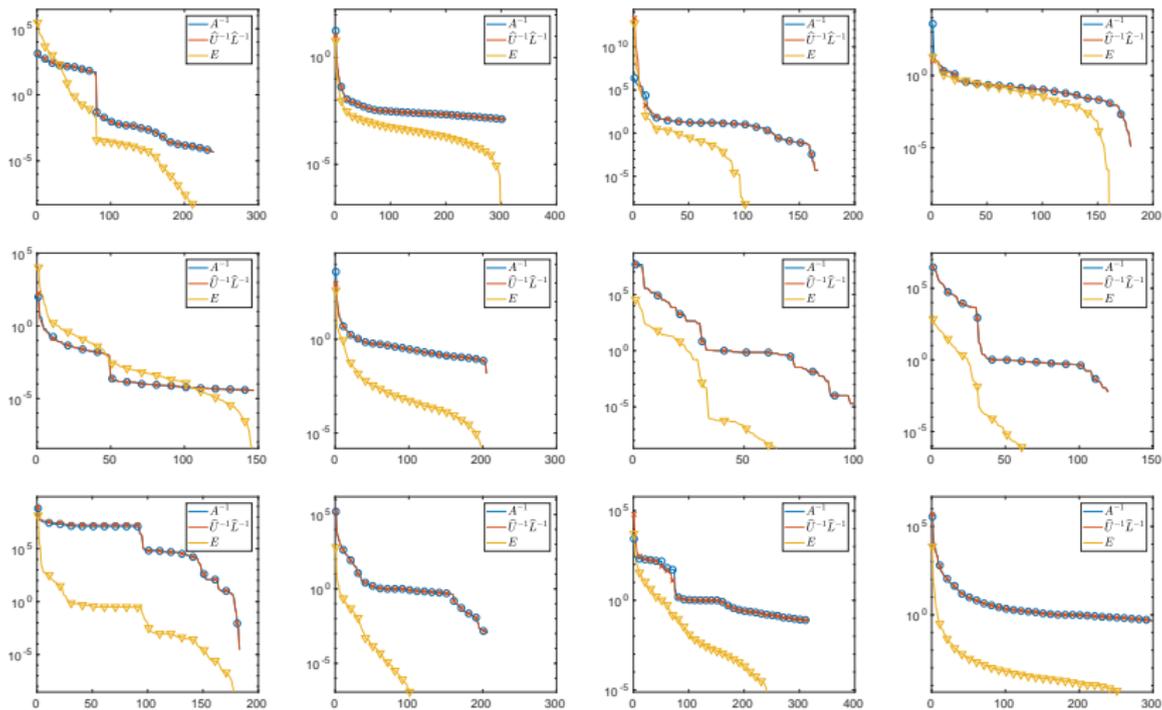
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Typical SV distributions of A^{-1} and E



We did **not** specifically select matrices for which A^{-1} is low-rank!

We need to build

$$\Pi_{E_k} = (I + E_k)^{-1} \Pi_{LU} = (I + E_k)^{-1} \hat{U}^{-1} \hat{L}^{-1}$$

where E_k is a rank- k approximation of $E = \hat{U}^{-1} \hat{L}^{-1} A - I$

E cannot be built explicitly! \Rightarrow Use **randomized** method

Algorithm 1 Randomized SVD via direct SVD of $V^T E$.

- 1: {Input: the error matrix $E = \hat{U}^{-1} \hat{L}^{-1} A - I$, stored implicitly.}
 - 2: Sample E : $S = E\Omega$, with Ω a $n \times (k + p)$ random matrix.
 - 3: Orthonormalize S : $V = \text{qr}(S)$.
 - 4: Compute SVD of $V^T E$: $X\Sigma Y^T = V^T E$.
 - 5: Truncate X, Σ, Y into X_k, Σ_k, Y_k .
 - 6: The SVD of E_k is given by $(VX_k)\Sigma_k Y_k^T$.
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$$\ell = k + p$$

	setup	solve
Π_{LU}	$\frac{2}{3}n^3$	$2n^2$
$\Pi_{E_k}^{(1)}$	$\frac{2}{3}n^3 + 8n^2\ell + O(n\ell^2)$	$2n^2 + O(nk)$

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Algorithm 1 Randomized SVD via row extraction.

- 1: {Input: the error matrix $E = \widehat{U}^{-1}\widehat{L}^{-1}A - I$, stored implicitly.}
- 2: Sample E : $S = E\Omega$, with Ω a $n \times (k+p)$ random FFT matrix.
- 3: Orthonormalize S : $V = \text{qr}(S)$.
- 4: Compute ID of V : $V = (I_k \ W)^T V_{(k,:)}$.
- 5: Extract $E_{(k,:)}$ and compute a QR factorization $E_{(k,:)}^T = QR$.
- 6: Compute SVD of $(I_k \ W)^T R^T$: $X\Sigma Y^T = (I_k \ W)^T R^T$.
- 7: Truncate X, Σ, Y into X_k, Σ_k, Y_k .
- 8: The SVD of E_k is given by $(VX_k)\Sigma_k Y_k^T$.

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$\Pi_{E_k}^{(3)}$	$\frac{2}{3}n^3 + 2n^2\ell + 4n^2 \log \ell + O(n\ell^2)$	$2n^2 + O(nk)$

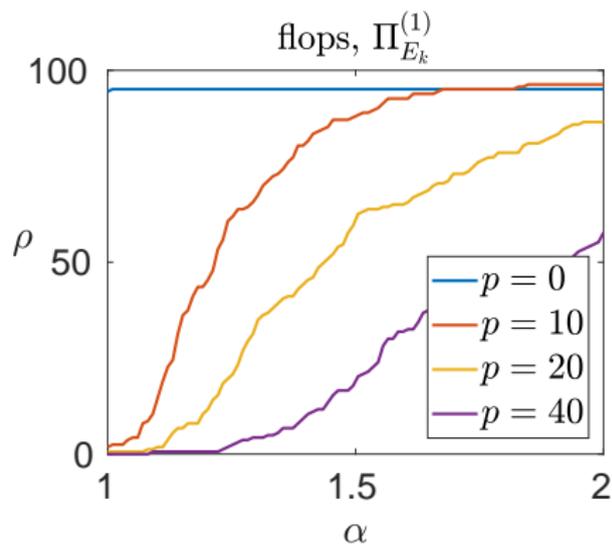
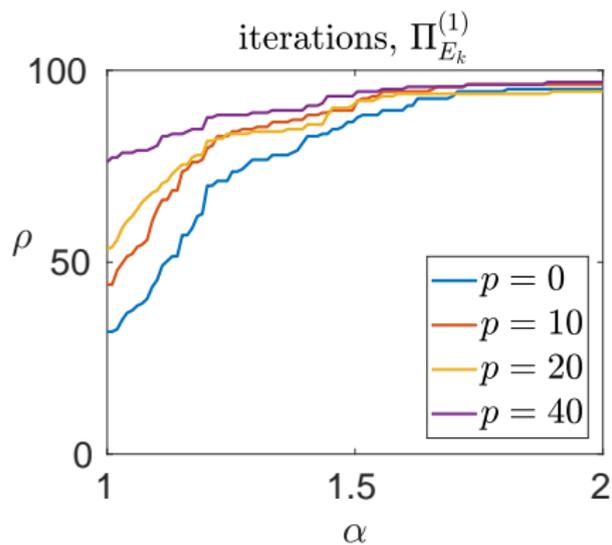
- Three types of approximate LU factorization:
 - Half-precision
 - Incomplete LU with drop tolerance $10^{-5} \leq \tau \leq 10^{-1}$
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- Iterative solver is GMRES-based iterative refinement with three precisions
 - FP64 working precision and residual is computed in FP128
 - Max nb of GMRES iterations per IR step is 100
 - Max nb of IR steps is 10

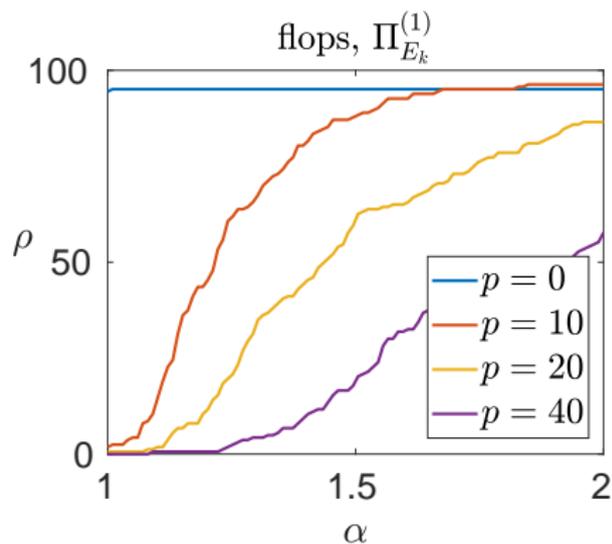
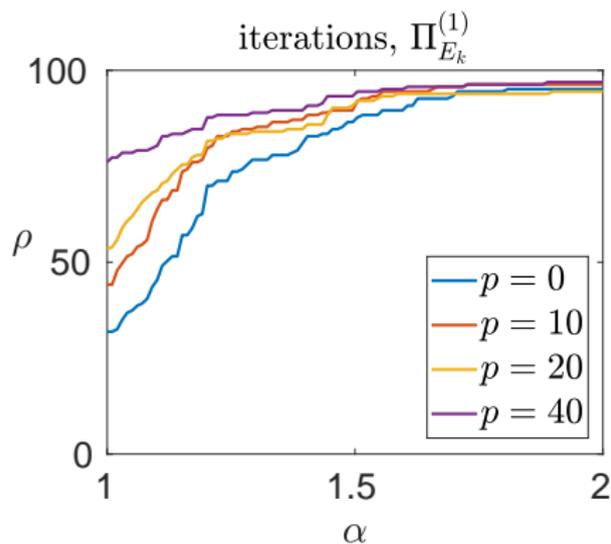
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 - $53 \leq n \leq 494$ and $10^3 \leq \kappa(A) \leq 10^{14}$
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 - 149 tests on 40 different matrices
- MATLAB code running on laptop
 - We measure nb of iterations and flops
 - Time is only estimated, not measured

Performance profile: ρ is the percentage of problems solved for less than $\alpha \times$ the cost of the best choice \Rightarrow **higher is better**

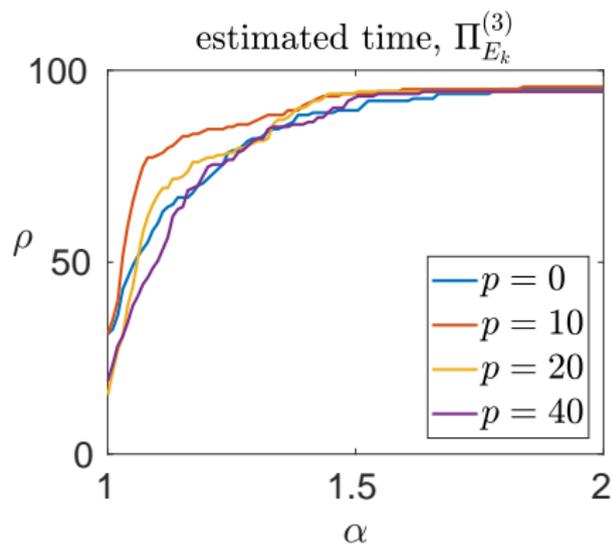
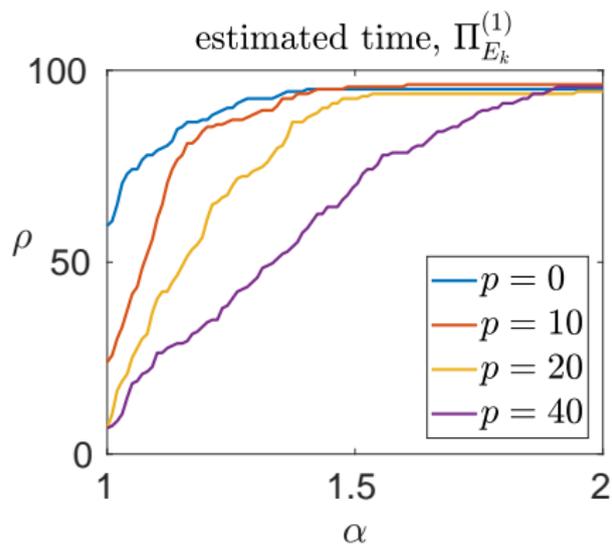


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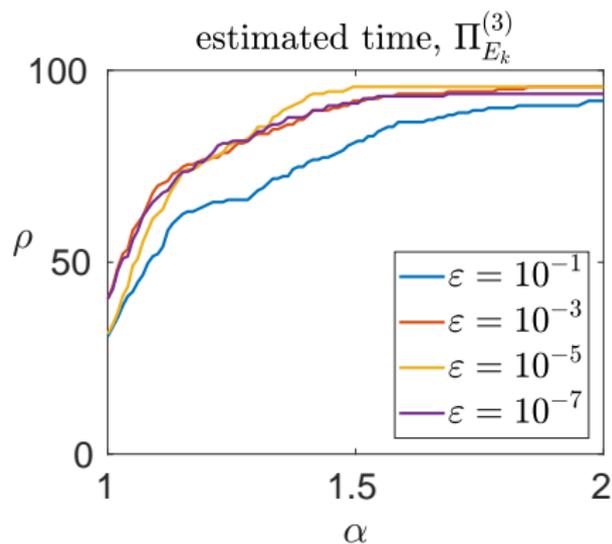
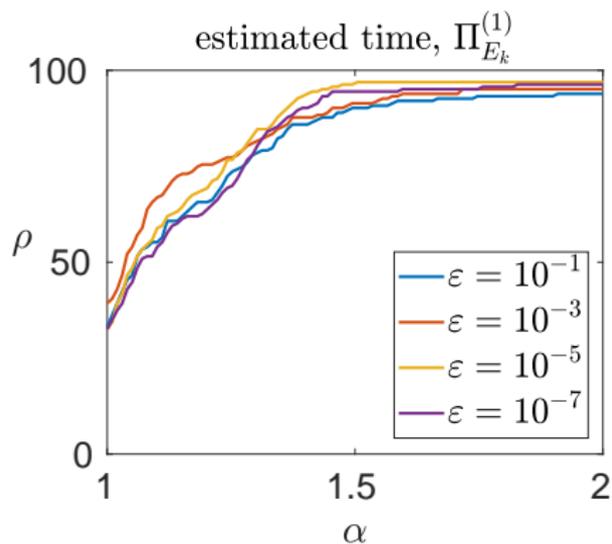
We seek a compromise between **number of iterations** and **flops** to minimize **time**, which we estimate assuming BLAS-2 is 10 \times slower than BLAS-3

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Need to set oversampling p differently depending on preconditioner variant

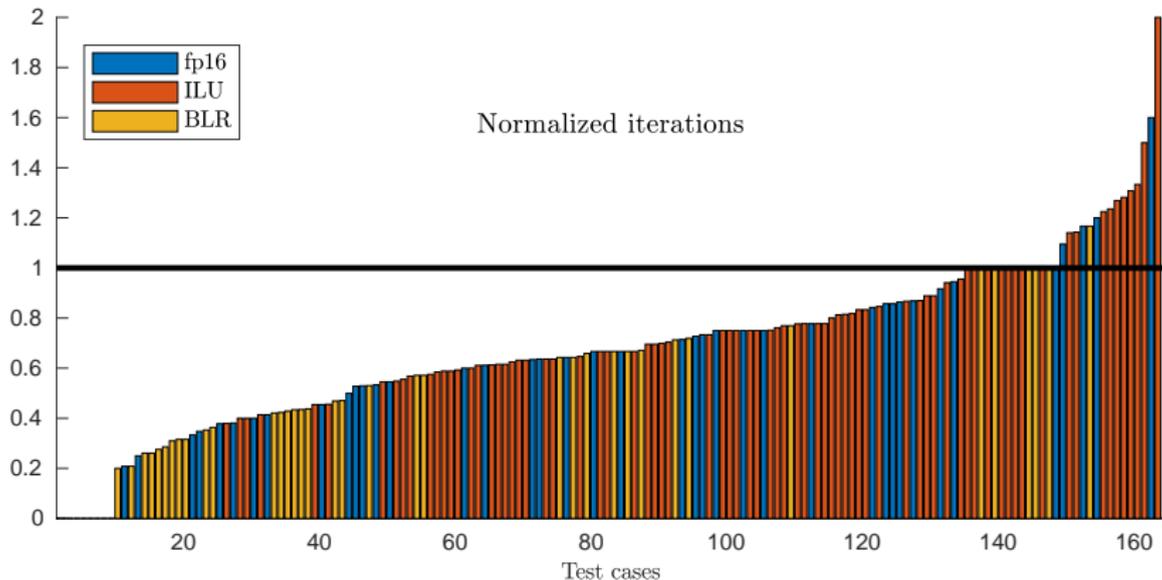
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Similar trend for low-rank threshold ε

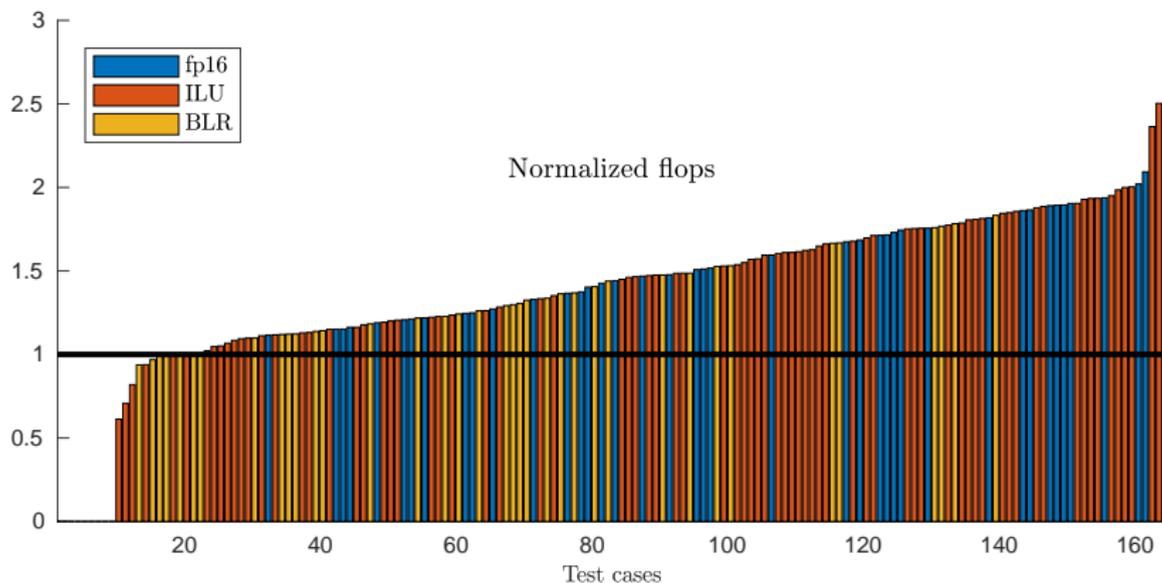
Results with black-box setting

Black-box setting: use $\Pi_{E_k}^{(3)}$ with $p = 10$ and $\varepsilon = 10^{-7}$



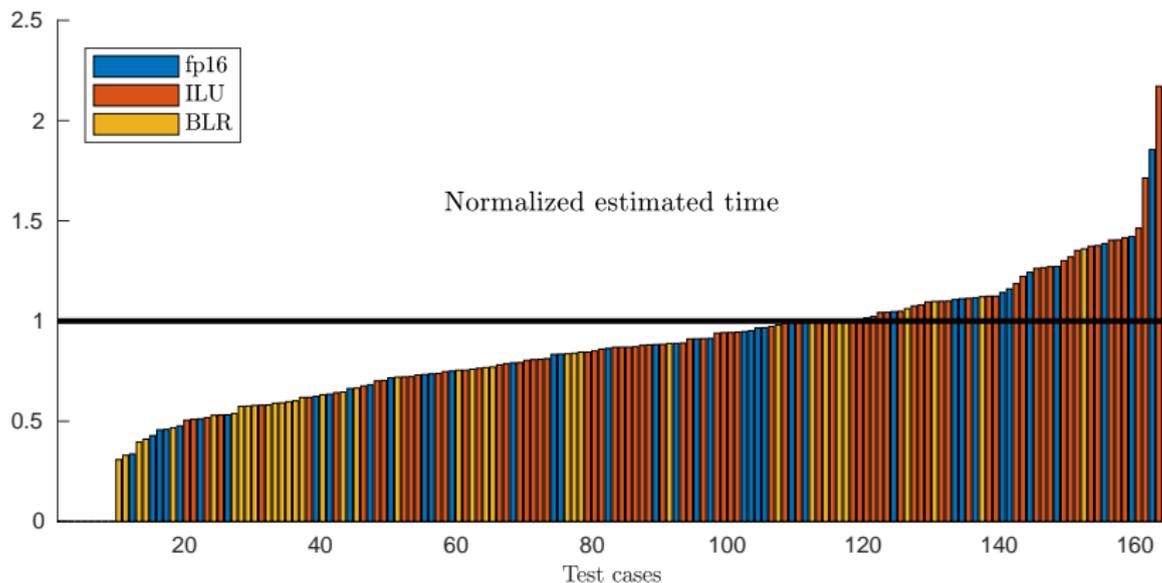
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Application to large-scale, sparse matrices

 P. R. Amestoy, A. Buttari, J.-Y. L'Excellent, and T. Mary, *Performance and Scalability of the Block Low-Rank Multifrontal Factorization on Multicore Architectures*.

Application to **BLR-MUMPS** sparse multifrontal solver
BLR threshold = 10^{-2} , iterate until converged to accuracy 10^{-9}

Matrix	n	Π_{LU}		Π_{E_k}	
		Iter.	Time	Iter.	Time
audikw_1	1.0M	691	1163	331	625
Bump_2911	2.9M	—	—	284	1708
Emilia_923	0.9M	174	304	136	267
Fault_639	0.6M	—	—	294	345
Ga41As41H72	0.3M	—	—	135	143
Hook_1498	1.5M	417	902	356	808
Si87H76	0.2M	—	—	131	116

Good potential to improve low-precision, low-memory BLR solvers

Summary

- **Ill-conditioned matrices** often have a **numerically low-rank inverse**
- **Theoretical justification** of why the error $E = \hat{U}^{-1}\hat{L}^{-1}A - I$ retains this property
- **Novel preconditioner** based on a low-rank approximation to the error to accelerate linear systems solution

Future work

- **High-performance** implementation for FP16 and ILU
- Well suited for **GPUs** (FP16 8× faster than FP32!)

Slides and paper available here

<http://personalpages.manchester.ac.uk/staff/theo.mary/>

Backup slides

Lemma

$$\sigma_i(X + \Delta X) \leq \sigma_i(X) (1 + \|X^{-1}\Delta X\|)$$

Apply lemma twice:

$$X = \hat{L}\hat{U} \text{ and } \Delta X = \Delta A \quad \Rightarrow \quad \sigma_i(A) \leq \sigma_i(\hat{L}\hat{U}) \overbrace{\left(1 + \|\hat{U}^{-1}\hat{L}^{-1}\Delta A\|\right)}^{\text{Maximum growth}}$$

$$X = A \text{ and } \Delta X = -\Delta A \quad \Rightarrow \quad \sigma_i(\hat{L}\hat{U}) \leq \sigma_i(A) \underbrace{\left(1 + \|A^{-1}\Delta A\|\right)}_{\text{Maximum shrinkage}}$$

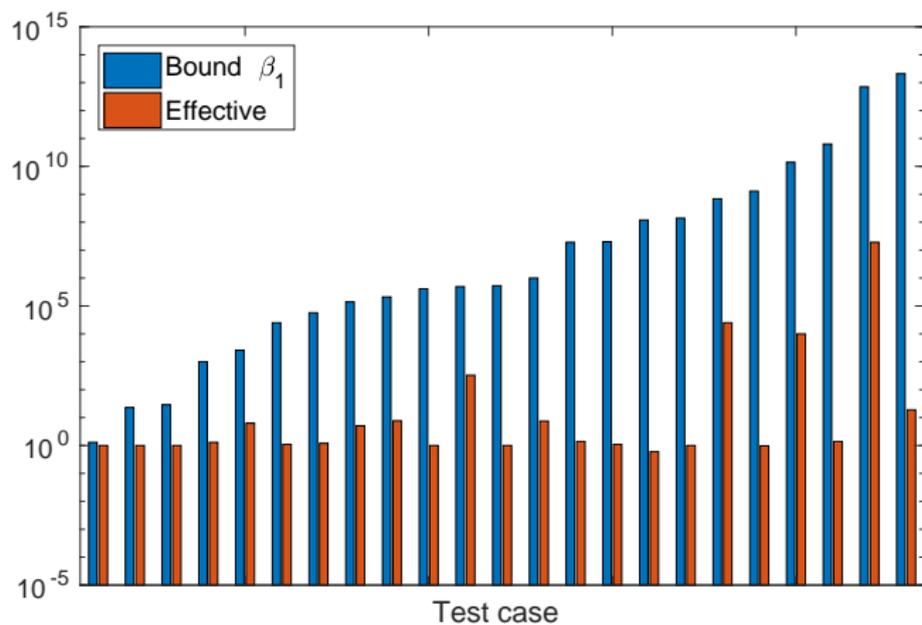
Theorem

$$\varepsilon_k(\hat{U}^{-1}\hat{L}^{-1}) \leq \beta_1 \varepsilon_k(A^{-1})$$

with

$$\beta_1 = (1 + \|A^{-1}\Delta A\|) \left(1 + \|\hat{U}^{-1}\hat{L}^{-1}\Delta A\|\right)$$

Bound β_1 is pessimistic



Theorem

$$\varepsilon_k(\hat{U}^{-1}\hat{L}^{-1}\Delta A) \leq \beta_2 \varepsilon_k(\hat{U}^{-1}\hat{L}^{-1})$$

with

$$\beta_2 = \frac{\|\hat{U}^{-1}\hat{L}^{-1}\| \|\Delta A\|}{\|\hat{U}^{-1}\hat{L}^{-1}\Delta A\|}$$

Corollary

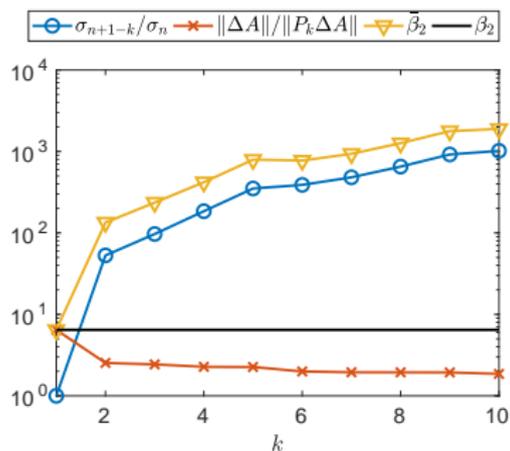
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Theorem

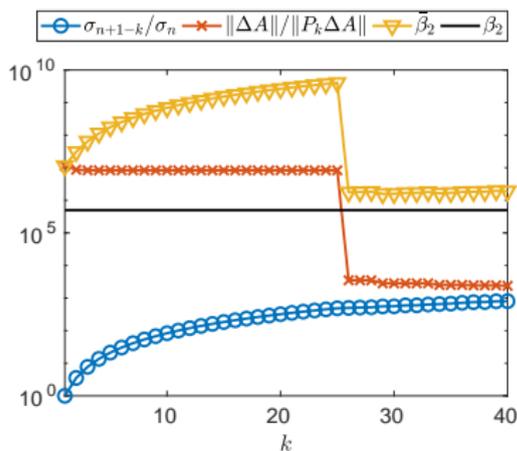
$$\beta_2 \leq \bar{\beta}_2 = \frac{\sigma_{n+1-k}(\hat{L}\hat{U})}{\sigma_n(\hat{L}\hat{U})} \frac{\|\Delta A\|}{\|P_k \Delta A\|}$$

with $P_k = X_k X_k^T$ and X_k the last k left singular vectors of $\hat{L}\hat{U}$.

Bound β_2 is also pessimistic



Typical ΔA



Special ΔA

