



A multicategorical approach to mixed linear-non-linear substitution

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Semantics and Programming Languages

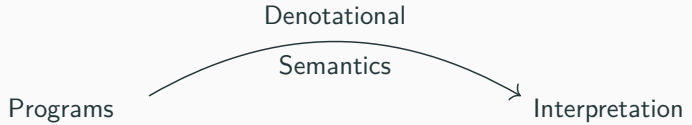
*Semantics is a key tool for **designing** programming languages, **formalization** and **proof** of programs all through the continuum from machine code to high level programming languages.*

Semantics and Programming Languages

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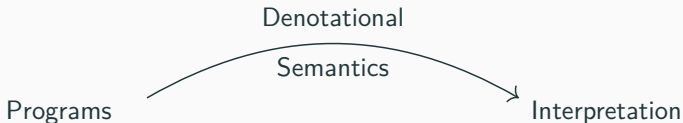
This talk is about

- Substitution
- Linearity and Non-linearity
- (multi-)Category Theory



```
import random
def flip(p: float) -> int:
    if random.random() < p:
        return 0
    else:
        return 1
```

→ $[0, 1] \xrightarrow{f} \mathcal{V}([0, 1])$
 $0.3 \mapsto 0.3\delta_0 + 0.7\delta_1$

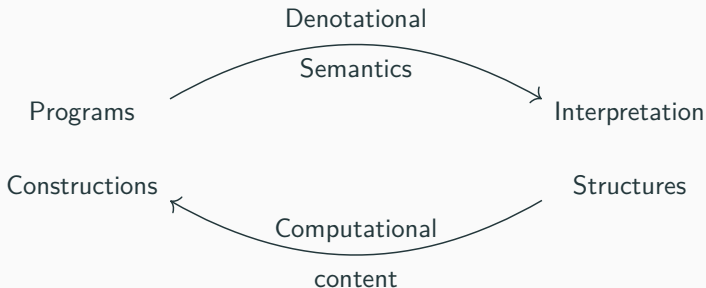


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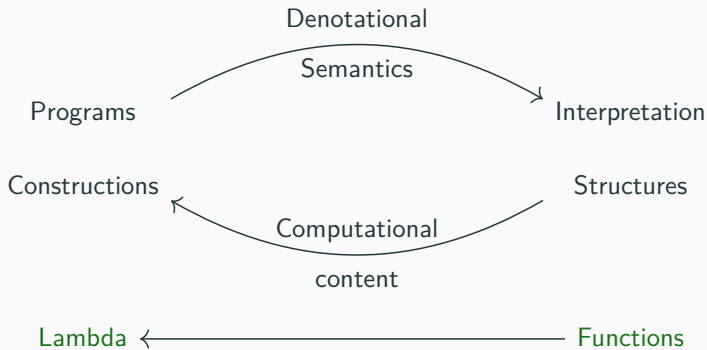
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$\longrightarrow$
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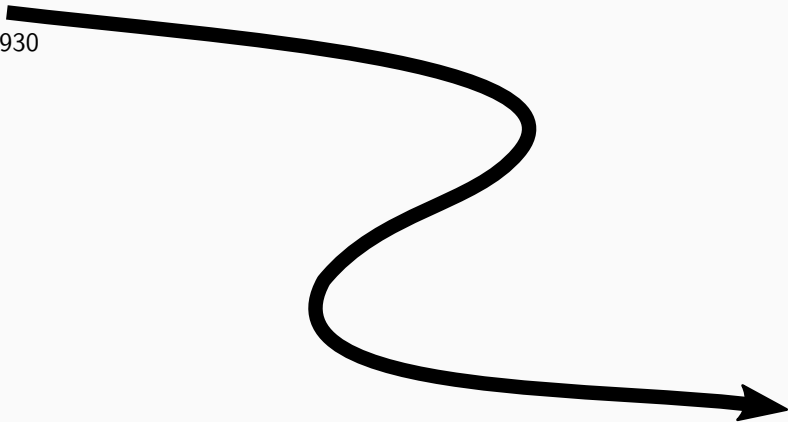
```
def shift(n: int) :
    return lambda s: s+n
```

Lambda-Calculus



Church

1930



1930: Church

Lambda-terms represent **computable functions**.

	Programs	Functions	
	M, N	$f, g : \mathbb{N} \rightarrow \mathbb{N}$	
Variable	x	x	Variable
Abstraction	$\lambda x.M$	$f : x \mapsto 5 * x * (x + 1) + 3$	Map
Application	$(\lambda x.M)N$	$f(g) = 5 * g * (g + 1) + 3$	Substitution



Lambda-Calculus

Church

Computers

1930

1940

1950





Church

Lambda-Calculus

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Operational and Denotational Semantics



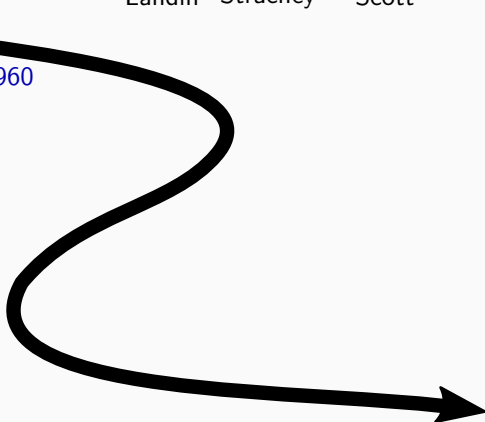
Landin



Strachey



Scott



1960: From syntax to semantics

Syntax describes how to write programs,
Semantics describes how and what programs compute.

Operational semantics describes program execution as transition system. (Landin 1966)

For λ -calculus, **substitution** in contexts

$$(\lambda x.M)N \rightarrow M[N/x]$$

Denotational Semantics denotes programs as functions acting on *values* and on *memory state*.

(Strachey 1960) (Scott 1969)

For pure λ -calculus, solving **equation**

$$D \stackrel{?}{=} \text{Var} + [D \rightarrow D] + \dots$$

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Continuous



Lambda-Calculus

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Operational and Denotational Semantics



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Proofs-Programs Category



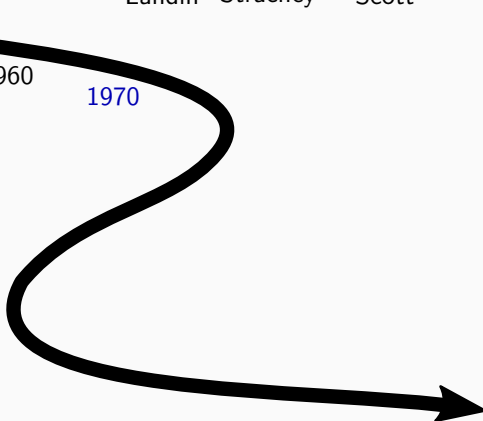
Curry



Howard



Lambek



1970: Computer Science - Logic - Category

Curry-Howard

λ -calculus

Program : Type

$M : A \Rightarrow B$

Logic

Proof : Formula

$$\frac{\pi}{A \Rightarrow B}$$

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Cartesian Closed Categories

$\llbracket M \rrbracket$: Morphism from context to output

$\llbracket A \Rightarrow B \rrbracket$: Object with

- evaluation: $ev : (A \Rightarrow B) \times A \rightarrow B$
- currying: $f : C \times A \rightarrow B$ corresponds to $\Lambda f : C \rightarrow (A \Rightarrow B)$

Lambek

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Proofs-Programs Category

Stability



Curry



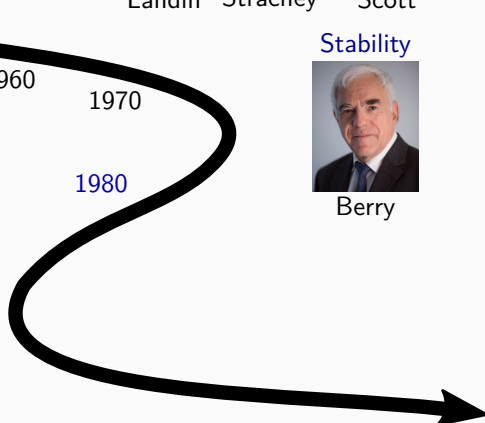
Howard



Lambek



Berry



1980: Sequential algorithms

PCF a typed functional languages such as Haskell or ML

Denotational Semantics

Scott Domains contain non sequential functions such as Parallel-Or.

Stability gets rid of this example, but does not characterize *sequentiality*

Sequential algorithm model uses the language of category (Berry-Curien 1982)

The **Full Abstraction** quest generates new models *Hypercoherence* (Ehrhard 1993) and *Game semantics* (Abramsky-Jagadeesan-Malacaria 1994), (Hyland-Ong 1995)



Church

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Operational and Denotational Semantics



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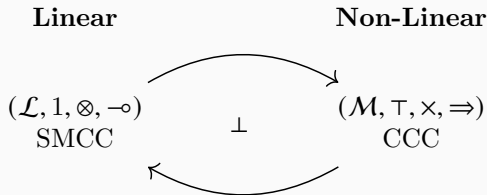
Linear Logic

1990: Linear Logic

Semantical observation: (Girard 1987)

$$A \xRightarrow{\text{Stable}} B \simeq !A \xrightarrow[\text{Linear}]{-\circ} B$$

Categorical models

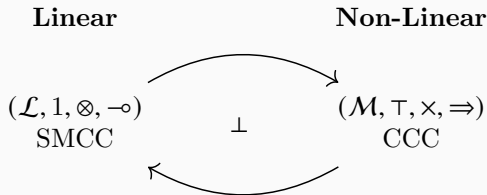


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Categorical models



Linear Type Systems influenced prototypes

(Berry, Girard, Pym, O'Hearn, Dreyer, Graydon Hoare. . .)

1991: Monads



Eugenio Moggi wrote *Notions of computation and Monads* and formalized computation and effects in categorical semantics.

Monad T

maybe monad $TA = \text{Nothing or } A$

TA denotes the computations of type A and come with

- multiplication $\mu : T^2A \rightarrow TA$ describes how to compose effects
- unit $\eta : A \rightarrow TA$ embeds effect-free computations into effectful computations

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Monads influenced the design of Haskell

(Plotkin, Power, Wadler, Jones. . .)

Influence of semantics on the design of programming languages

Challenges

- **Machine learning and Automatic Differentiation** (Tensorflow, Julia, Swift, Pytorch, JAX, . . .),
- **Statistical Learning** (Anglican, Gen, Birch, Pyro, . . .),
- **Quantic** (Quipper, Choir, ZX-calculus, . . .).

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Key concepts

- **Substitution** (replace) and evaluation
- **Compositionnality** (compute from smaller blocks)
- **Higher-order** (programs with programs as parameters)

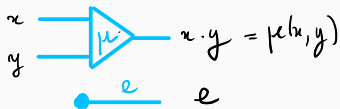
Theory of Substitution

Examples

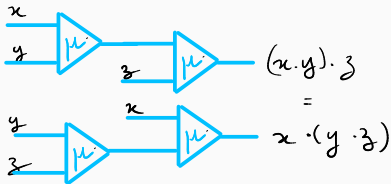
Hopf Algebras

What is a group in Set?

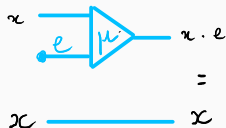
A Monoid



Associativity law



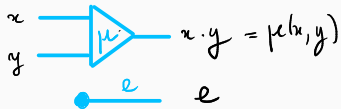
Unit law



Hopf Algebras

What is a group in Set?

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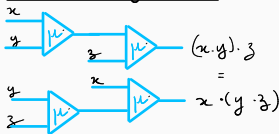


with an

Inverse



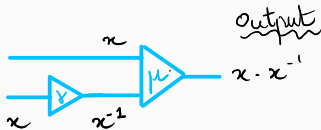
Associativity law



Inverse law $x \cdot x^{-1} = e$

Input

$x - ?$



Unit law



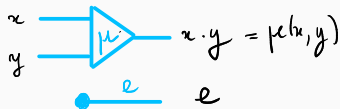
$x - ?$

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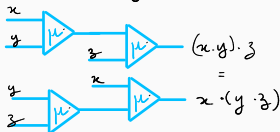


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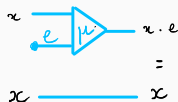
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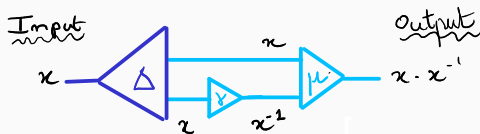
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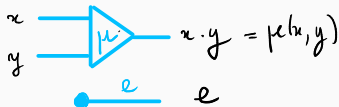
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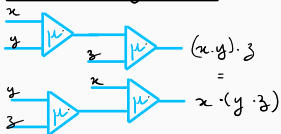
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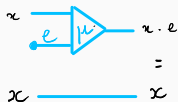
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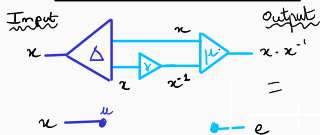


with an

Inverse



Inverse law $x \cdot x^{-1} = e$



$\mu: X \times X \rightarrow X$ satisfying unit, associativity, inverse laws.

$e: T \rightarrow X$

$\Delta: X \rightarrow X \times X$

$u: X \rightarrow T$

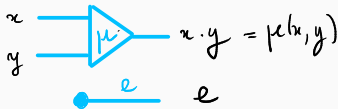
$\gamma: X \rightarrow X$

} Exists because Set is cartesian

Hopf Algebras

What is a group in Set? ~~Vect~~

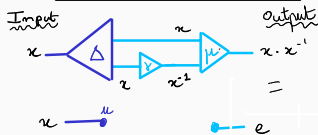
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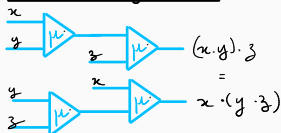
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Inverse law $x \cdot x^{-1} = e$



Associativity law



Unit law



HOPF ALGEBRA

$\mu: X \otimes X \rightarrow X$

$e: 1 \rightarrow X$

$\Delta: X \rightarrow X \otimes X$

$u: X \rightarrow 1$

$\gamma: X \rightarrow X$

satisfying unit, associativity, inverse laws.

Expts because

Set is ~~not~~ cartesian for it

Consumable computational resources

```
1  L = 5*[0]
2  M = []
3  for i in range(5):
4      M.append(L)
5  M[0][0] = 1
6
7  >>> M
8  [[1, 0, 0, 0, 0],
9   [1, 0, 0, 0, 0],
10  [1, 0, 0, 0, 0],
11  [1, 0, 0, 0, 0],
12  [1, 0, 0, 0, 0]]
```

Consumable computational resources

- Allocated memory
- Open file handles
- Socket connections

Linear type influence

- Uniqueness types, Ownership, borrowed pointers
- Mezzo, Cyclone, Rust, Idris...

Yet, programs and proofs are **not** linear in general as one needs to copy values and to reuse lemmas.

What is a linear-non-linear semantics ?

Equivalent Probabilistic Programs?

```
1  let x = sample (flip p)
2  in if x
3    then if x
4          then 1
5          else 2
6    else if x
7          then 2
8          else 3
9
```

outputs:

- 1 with probability p
- 2 with probability 0
- 3 with probability $(1 - p)$

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outputs:

- 1 with probability p^2
- 2 with probability $2p(1 - p)$
- 3 with probability $(1 - p)^2$

Equivalent Probabilistic Programs?

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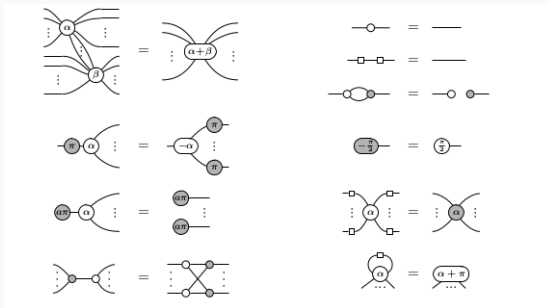
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Substitution of effectful constructs is subtle due to duplication.

Quantum Programming

ZX-Calculus (<https://zxcalculus.com/>)



Linear and non-linear resources

- Quantum resources can be used once : they are **Linear**
- Classical resource can be used at will : they are **non-Linear**

Semantical observation: λ -terms can be interpreted by smooth functions, hence differentiation.

	Programs	Functions	
	M, N	f, g	
Variable	x	x	Variable
Abstraction	$\lambda x.M$	$f : x \mapsto f(x)$	Map
Application	$(\lambda x.M)N$	$f \circ g$	Composition
Linear Application	$D\lambda x.M \cdot N$	$Df_x \circ g$	Derivation

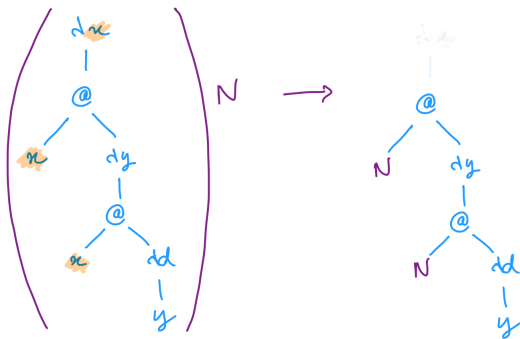
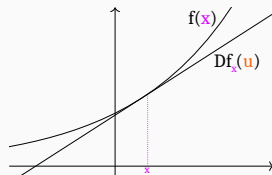
Linear and Non-Linear substitutions in Differential λ -calculus

Linear and Non Linear Substitutions

$$(\lambda x.M)N \rightarrow M[x \backslash N]$$

$$D\lambda x.M \cdot N \rightarrow \lambda x. \left(\frac{\partial M}{\partial x} \cdot N \right)$$

Linear approximation



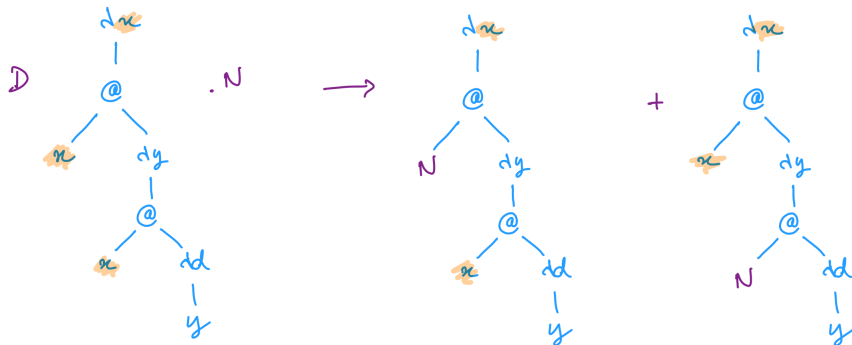
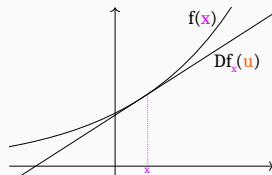
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Linear and Non Linear Substitutions

$$(\lambda x.M)N \rightarrow M[x \setminus N]$$

$$D\lambda x.M \cdot N \rightarrow \lambda x. \left(\frac{\partial M}{\partial x} \cdot N \right)$$

Linear approximation



Theory of Substitution

Linear-non-linear Multicategories

Multiplicative Linear Logic

Linear Type system

$$\frac{}{x : a \quad \vdash x : a} \qquad \frac{\Gamma, x : a \quad \vdash t : b}{\Gamma \quad \vdash \lambda x^a. t : a \multimap b}$$

$$\frac{\Gamma \quad \vdash s : a \multimap b \quad \Gamma' \quad \vdash t : a}{\Gamma, \Gamma' \quad \vdash \langle s \rangle t : b}$$

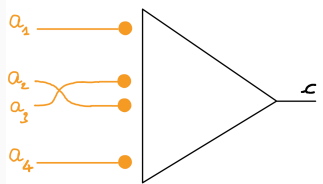
Multicategorical axiomatization

$$x_1 : a_1, \dots, x_\ell : a_\ell \vdash t : c$$

denoted as

$$a_1, \dots, a_\ell \multimap c.$$

symetric multicategory:



Multiplicative Linear Logic

Linear Type system

$$\frac{}{x : a \quad \vdash x : a} \quad \frac{\Gamma, x : a \quad \vdash t : b}{\Gamma \quad \vdash \lambda x^a. t : a \multimap b}$$

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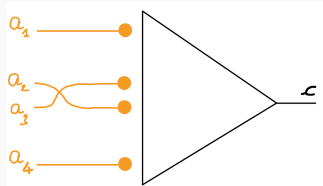
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Lambda-calculus

Non-Linear Type system

$$\frac{}{\Delta, x : \underline{b} \vdash x : \underline{b}} \quad \frac{\Delta, x : \underline{a} \vdash t : b}{\Delta \vdash \lambda x^{\underline{a}}. t : \underline{a} \rightarrow b}$$
$$\frac{\Delta \vdash s : a \rightarrow b \quad \Delta \vdash t : a}{\Delta \vdash (s)t : b}$$

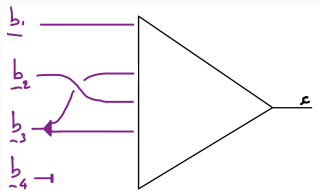
Multicategorical axiomatization:

cartesian multicategory (a clone):

$$y_1 : \underline{b}_1, \dots, y_n : \underline{b}_n \vdash t : c$$

denoted as

$$\underline{b}_1, \dots, \underline{b}_n \rightarrow c.$$



Lambda-calculus

Non-Linear Type system

$$\frac{}{\Delta, x : \underline{b} \vdash x : \underline{b}} \quad \frac{\Delta, x : \underline{a} \vdash t : b}{\Delta \vdash \lambda x^{\underline{a}}. t : \underline{a} \rightarrow b}$$

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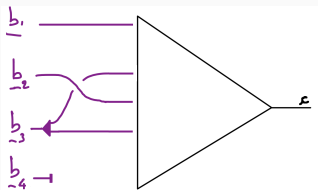
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A term calculus for Linear-non-linear Logic

(Benton-Bierman-de Paiva-Hyland 1993, Barber 1996)

$$\boxed{\underbrace{x_1 : a_1, \dots, x_\ell : a_\ell}_{\text{Linear}} \mid \underbrace{y_1 : \underline{b}_1, \dots, y_n : \underline{b}_n}_{\text{Non-Linear}} \vdash t : c}$$

Linear rules:

$$\frac{}{x : a \mid \Delta \vdash x : a} \quad \frac{\Gamma, x : a \mid \Delta \vdash t : b}{\Gamma \mid \Delta \vdash \lambda x^a. t : a \multimap b}$$

$$\frac{\Gamma \mid \Delta \vdash s : a \multimap b \quad \Gamma' \mid \Delta \vdash t : a}{\Gamma, \Gamma' \mid \Delta \vdash \langle s \rangle t : b}$$

Non-linear rules:

$$\frac{}{\Gamma \mid \Delta, x : \underline{b} \vdash x : \underline{b}} \quad \frac{\Gamma \mid \Delta, x : \underline{a} \vdash t : b}{\Gamma \mid \Delta \vdash \lambda x^{\underline{a}}. t : \underline{a} \multimap b}$$

$$\frac{\Gamma \mid \Delta \vdash s : a \multimap b \quad \cdot \mid \Delta \vdash t : a}{\Gamma \mid \Delta \vdash (s)t : b}$$

Linear-non-linear rule:

$$\frac{\Gamma, x : a \mid \Delta \vdash t : b}{\Gamma \mid \Delta, x : \underline{a} \vdash t : b}$$

A term calculus for Linear-non-linear Logic

(Benton-Bierman-de Paiva-Hyland 1993, Barber 1996)

$$\underbrace{x_1 : a_1, \dots, x_\ell : a_\ell}_{\text{Linear}} \mid \underbrace{y_1 : \underline{b}_1, \dots, y_n : \underline{b}_n}_{\text{Non-Linear}} \vdash t : c$$

Linear rules:

$$\frac{}{x : a \mid \Delta \vdash x : a} \quad \frac{\Gamma, x : a \mid \Delta \vdash t : b}{\Gamma \mid \Delta \vdash \lambda x^a. t : a \multimap b}$$

$$\frac{\Gamma \mid \Delta \vdash s : a \multimap b \quad \Gamma' \mid \Delta \vdash t : a}{\Gamma, \Gamma' \mid \Delta \vdash \langle s \rangle t : b}$$

Non-linear rules:

$$\frac{}{\Gamma \mid \Delta, x : \underline{b} \vdash x : \underline{b}} \quad \frac{\Gamma \mid \Delta, x : \underline{a} \vdash t : b}{\Gamma \mid \Delta \vdash \lambda x^{\underline{a}}. t : \underline{a} \multimap b}$$

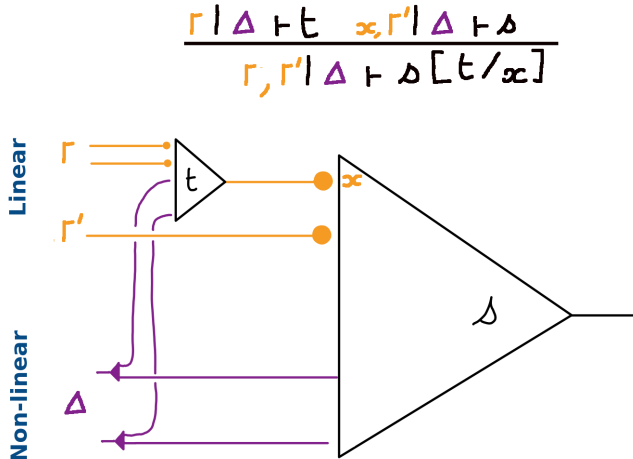
$$\frac{\Gamma \mid \Delta \vdash s : a \multimap b \quad \cdot \mid \Delta \vdash t : a}{\Gamma \mid \Delta \vdash (s)t : b}$$

Linear-non-linear rule:

$$\frac{\Gamma, x : a \mid \Delta \vdash t : b}{\Gamma \mid \Delta, x : \underline{a} \vdash t : b}$$

A term calculus for Linear-non-linear Logic

(Benton-Bierman-de Paiva-Hyland 1993, Barber 1996)



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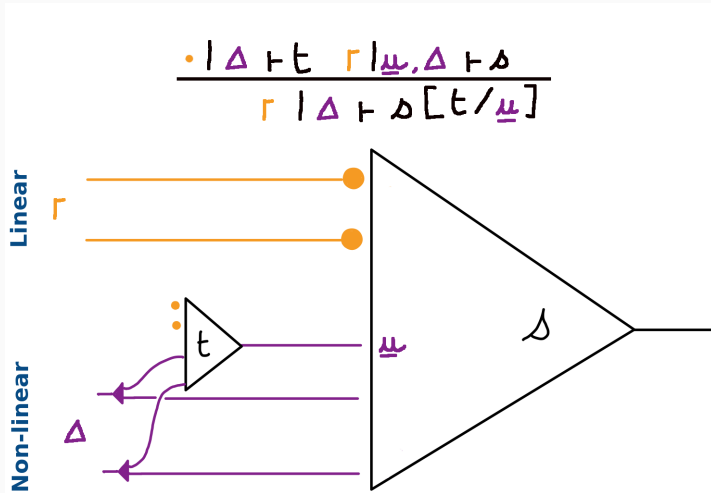
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Linear-non-linear rule:

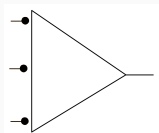
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Multicategories

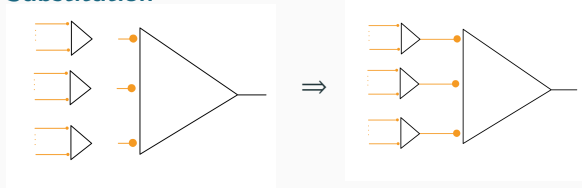
Profunctors and context 2-Monads

A Multicategory

Operations and



Substitution



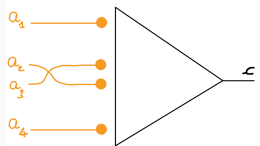
$\mathcal{T}A$ represent sequences of input types $\langle a_1, \dots, a_n \rangle$

- **Monad:** Concatenate sequences of sequences $\mathcal{T}\mathcal{T}A \rightarrow \mathcal{T}A$
- **Extend:** $\mathcal{T}$ from inputs to operations

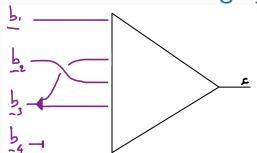
The multicategory $M : \mathcal{T}A \leftrightarrow A$ is given by the set of operations $M(\langle a_1, \dots, a_n \rangle, b)$

How to build a mixed multicategory ?

Symmetric Multicategory

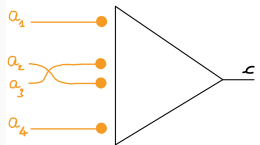


Cartesian Multicategory



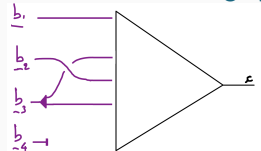
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Symmetric Multicategory



$\mathcal{L}(X)$ free Symetric Monoidal
Categories over $X: \langle a_1, \dots, a_\ell \rangle$

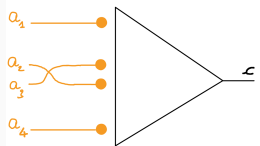
Cartesian Multicategory



$\mathcal{M}(X)$ free category with finite
products over $X: \langle \underline{b}_1, \dots, \underline{b}_n \rangle$

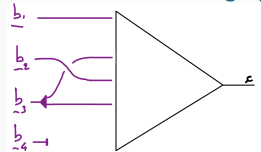
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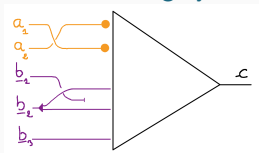
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Mixed Linear-Non-Linear Multicategory



What is the mixed Linear-non-linear context monad ?

$$\mathcal{Q}(X) : \langle a_1, \dots, a_\ell, \underline{b}_1, \dots, \underline{b}_n \rangle$$

What is $\mathcal{Q}$ -substitution?

A Colimit construction

To build the Linear-non-linear monad

colimits induced by a map in a category $\mathcal{K}$

If $\lambda : A \rightarrow B$ is a map in $\mathcal{K}$, then the induced

colimit is

$$\begin{array}{ccc} A & & \\ \lambda \downarrow & \searrow k & \\ B & \xrightarrow{\ell} & C \end{array}$$

■ for any

$$\begin{array}{ccc} A & & \\ \lambda \downarrow & \searrow f & \\ B & \xrightarrow{g} & D \end{array} = \begin{array}{ccc} A & & \\ \lambda \downarrow & \searrow k & \\ B & \xrightarrow{\ell} & C \end{array} \xrightarrow{\exists! r} D$$

Colax colimits induced by a map in a 2-category $\mathcal{K}$

If $\lambda : A \rightarrow B$ is a map in $\mathcal{K}$, then the induced **colax** colimit is

$$\begin{array}{ccc} A & & \\ \lambda \downarrow & \nearrow \alpha & \searrow k \\ B & \xrightarrow{\ell} & C \end{array}$$

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There are two universal aspects for 1-cells and 2-cells

■ for any $\begin{array}{ccc} A & & \\ \lambda \downarrow & \nearrow \phi & \searrow f \\ B & \xrightarrow{g} & D \end{array} = \begin{array}{ccc} A & & \\ \lambda \downarrow & \nearrow \alpha & \searrow k \\ B & \xrightarrow{\ell} & C \end{array} \cdots \exists! r \cdots \rightarrow D$

■ for any $\begin{array}{ccc} A & & \\ \lambda \downarrow & \nearrow \phi & \searrow f' \\ B & \xrightarrow{g} & D \end{array} = \begin{array}{ccc} A & & \\ \lambda \downarrow & \nearrow \phi' & \searrow f' \\ B & \xrightarrow{g} & D \end{array} \cdots \exists! r \xRightarrow{\tau} r' \text{ s.t.}$

$$A \begin{array}{c} \xrightarrow{f'} \\ \rho \uparrow \\ \xrightarrow{f} \end{array} D = A \xrightarrow{k} C \begin{array}{c} \xrightarrow{r'} \\ \tau \uparrow \\ \xrightarrow{r} \end{array} D$$

$$B \begin{array}{c} \xrightarrow{g'} \\ \sigma \uparrow \\ \xrightarrow{g} \end{array} D = B \xrightarrow{\ell} C \begin{array}{c} \xrightarrow{r'} \\ \tau \uparrow \\ \xrightarrow{r} \end{array} D$$

Mixing Linear and Non-Linear contexts via a colimit

Remark:

- Every category with products is a symmetric strict monoidal category

$$\lambda_X : \langle a_1, \dots, a_\ell \rangle \in \mathcal{L}X \mapsto \langle \underline{a}_1, \dots, \underline{a}_\ell \rangle \in \mathcal{M}X$$

Solution: Colax Colimit over λ in the 2-category of SymStMonCat

$$\begin{array}{ccc} \mathcal{L}X & & \\ \lambda_X \downarrow & \nearrow \alpha_X & \searrow k_X \\ \mathcal{M}X & \xrightarrow{\ell_X} & \mathcal{Q}X \end{array}$$

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$$\alpha_X, \langle a_1, \dots, a_\ell \rangle \in \mathcal{Q}X(\langle \cdot \mid \underline{a}_1, \dots, \underline{a}_\ell \rangle, \langle a_1, \dots, a_\ell \mid \cdot \rangle)$$

Mixing Linear and Non-Linear contexts via a colimit

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A Colimit construction

Q is a 2-monad on $\mathbf{Cat}$ and Q -algebras

A general colax colimit construction on 2-monads

Let $\lambda : \mathcal{L} \rightarrow \mathcal{M}$ a map of 2-monad on **Cat**.
If $\mathcal{L}$ -algebras has colimits, then the colimit is

$$\begin{array}{ccc} \mathcal{L}X & & \\ \lambda_X \downarrow & \nearrow \alpha_X & \\ \mathcal{M}X & \xrightarrow{\ell_X} & \mathcal{Q}X \end{array}$$

Theorem

- $\mathcal{Q}$ is a 2-monad on **Cat**.
- Characterization of $\mathcal{Q}$ -algebras

On going work (Galal-Hyland)

- $\mathcal{Q}$ -multicategories enjoy correct substitution

Take home:

- **Semantics** influence design of Programming Languages
- **Substitution** is subtle and important
- New combination of 2-monads through a **2-colimit**
- A first step towards understanding substitution with **mixed** variables through multicategories

The linear-non-linear substitution 2-monad (Hyland, T. 2020)

<https://arxiv.org/abs/2005.09559>

"The purpose of abstraction is *not* to be vague, but to create a new semantic level in which one can be absolutely precise".

(E. Dijkstra, The Humble Programmer, ACM Turing Lecture, 1972)