

# Intersection of regular signal-event (timed) languages

Béatrice Bérard

LAMSADE

Université Paris-Dauphine & CNRS

Beatrice.Berard@dauphine.fr

Joint work with Paul Gastin and Antoine Petit

FORMATS, September 26th, 2006

# Outline

**Introduction**

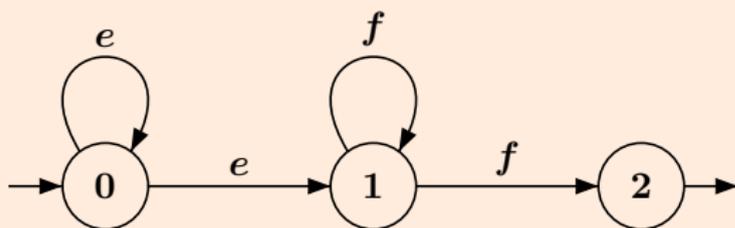
**Signal-Event (Timed) Words and Automata**

**Closure under intersection**

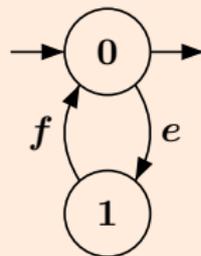
**Conclusion**

# Closure under intersection

is well known for regular languages



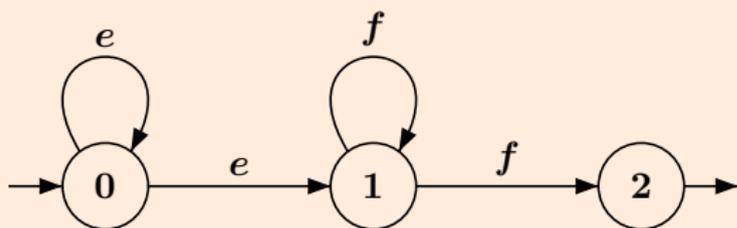
accepts  $L_1 = e^+ f^+$



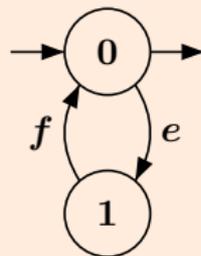
accepts  $L_2 = (ef)^*$

# Closure under intersection

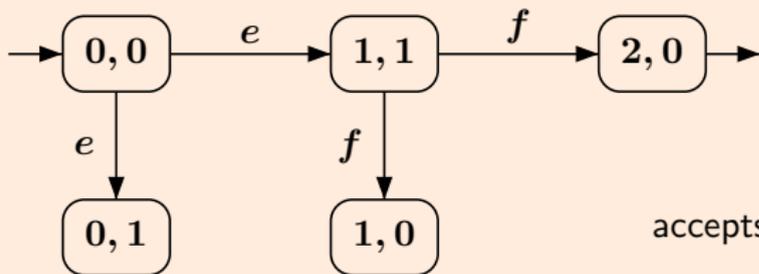
is well known for regular languages



accepts  $L_1 = e^+ f^+$



accepts  $L_2 = (ef)^*$



accepts  $L_1 \cap L_2 = \{ef\}$

# Closure under intersection

is a nice property

An implementation  $\mathcal{I} = \mathcal{L}(\mathcal{M})$  cannot behave badly as specified by  $\mathcal{B} = \mathcal{L}(\mathcal{P})$ :

$$\mathcal{L}(\mathcal{M}) \cap \mathcal{L}(\mathcal{P}) = \emptyset$$

Build a machine  $\mathcal{A}$  in the same class as  $\mathcal{M}$  and  $\mathcal{P}$  such that  $\mathcal{L}(\mathcal{A}) = \mathcal{L}(\mathcal{M}) \cap \mathcal{L}(\mathcal{P})$  and test emptiness in this class.

Many other applications (see next talk).

The construction has been extended to

- ▶ automata for infinite words: Büchi
- ▶ automata for timed words: Alur - Dill 1990

automata for signal-event words

?

# Closure under intersection

is a nice property

An implementation  $\mathcal{I} = \mathcal{L}(\mathcal{M})$  cannot behave badly as specified by  $\mathcal{B} = \mathcal{L}(\mathcal{P})$ :

$$\mathcal{L}(\mathcal{M}) \cap \mathcal{L}(\mathcal{P}) = \emptyset$$

Build a machine  $\mathcal{A}$  in the same class as  $\mathcal{M}$  and  $\mathcal{P}$  such that  $\mathcal{L}(\mathcal{A}) = \mathcal{L}(\mathcal{M}) \cap \mathcal{L}(\mathcal{P})$  and test emptiness in this class.

Many other applications (see next talk).

The construction has been extended to

- ▶ automata for infinite words: Büchi
- ▶ automata for timed words: Alur - Dill 1990

automata for signal-event words

?

# Closure under intersection

is a nice property

An implementation  $\mathcal{I} = \mathcal{L}(\mathcal{M})$  cannot behave badly as specified by  $\mathcal{B} = \mathcal{L}(\mathcal{P})$ :

$$\mathcal{L}(\mathcal{M}) \cap \mathcal{L}(\mathcal{P}) = \emptyset$$

Build a machine  $\mathcal{A}$  in the same class as  $\mathcal{M}$  and  $\mathcal{P}$  such that  $\mathcal{L}(\mathcal{A}) = \mathcal{L}(\mathcal{M}) \cap \mathcal{L}(\mathcal{P})$  and test emptiness in this class.

Many other applications (see next talk).

The construction has been extended to

- ▶ automata for infinite words: Büchi
- ▶ automata for timed words: Alur - Dill 1990

automata for signal-event words

?

# Closure under intersection

is a nice property

An implementation  $\mathcal{I} = \mathcal{L}(\mathcal{M})$  cannot behave badly as specified by  $\mathcal{B} = \mathcal{L}(\mathcal{P})$ :

$$\mathcal{L}(\mathcal{M}) \cap \mathcal{L}(\mathcal{P}) = \emptyset$$

Build a machine  $\mathcal{A}$  in the same class as  $\mathcal{M}$  and  $\mathcal{P}$  such that  $\mathcal{L}(\mathcal{A}) = \mathcal{L}(\mathcal{M}) \cap \mathcal{L}(\mathcal{P})$  and test emptiness in this class.

Many other applications (see next talk).

The construction has been extended to

- ▶ automata for infinite words: Büchi
- ▶ automata for timed words: Alur - Dill 1990

automata for signal-event words

?

# Outline

Introduction

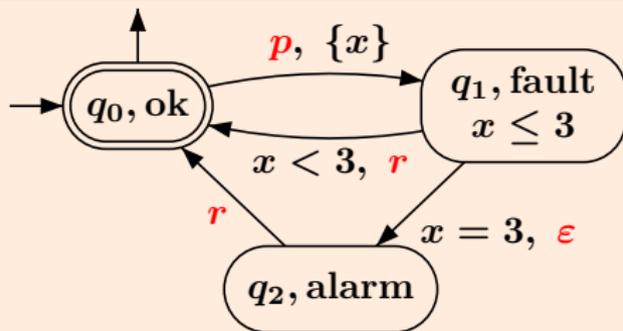
Signal-Event (Timed) Words and Automata

Closure under intersection

Conclusion

# Signal-Event (Timed) Automata

Asarin - Caspi - Maler 2002



$x$ : clock

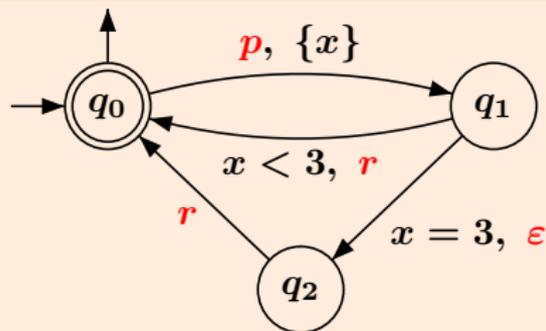
$$\begin{bmatrix} q_0 \\ 0 \end{bmatrix} \xrightarrow{8.3} \begin{bmatrix} q_0 \\ 8.2 \end{bmatrix} \xrightarrow{p} \begin{bmatrix} q_1 \\ 0 \end{bmatrix} \dots$$

Signal-event word :  $ok^{8.2} p \text{ fault}^3 \text{ alarm}^{1.5} r \dots$

- ▶ States emit (possibly hidden) signals
- ▶ Transitions emit (instantaneous, possibly silent) events
- ▶ Clocks are used for time constraints

# Signal-Event (Timed) Automata

Alur - Dill 1990



$x$ : clock

$$\begin{bmatrix} q_0 \\ 0 \end{bmatrix} \xrightarrow{8.3} \begin{bmatrix} q_0 \\ 8.2 \end{bmatrix} \xrightarrow{p} \begin{bmatrix} q_1 \\ 0 \end{bmatrix} \dots$$

time-event automata and time-event words:

$8.2 \ p \ 4.5 \ r \dots$  or equivalently  $(p, 8.3)(r, 12.7) \dots$

- ▶ States emit (possibly hidden) signals
- ▶ Transitions emit (instantaneous, possibly silent) events
- ▶ Clocks are used for time constraints

# Signal-Event (Timed) Words

- ▶  $\Sigma_e$  finite set of (instantaneous) events
- ▶  $\Sigma_s$  finite set of signals
- ▶  $\mathbb{T}$  time domain,  $\overline{\mathbb{T}} = \mathbb{T} \cup \{\infty\}$
- ▶  $\Sigma = \Sigma_e \cup (\Sigma_s \times \mathbb{T})$
- ▶ Notation:  $a^d$  for  $(a, d) \in \Sigma_s \times \overline{\mathbb{T}}$
- ▶  $\Sigma^\infty$  : set of finite and infinite words over  $\Sigma$

# Signal-Event (Timed) Words

- ▶  $\Sigma_e$  finite set of (instantaneous) events
- ▶  $\Sigma_s$  finite set of signals
- ▶  $\mathbb{T}$  time domain,  $\overline{\mathbb{T}} = \mathbb{T} \cup \{\infty\}$
- ▶  $\Sigma = \Sigma_e \cup (\Sigma_s \times \mathbb{T})$
- ▶ Notation:  $a^d$  for  $(a, d) \in \Sigma_s \times \overline{\mathbb{T}}$
- ▶  $\Sigma^\infty$  : set of finite and infinite words over  $\Sigma$

# Signal-Event (Timed) Words

- ▶  $\Sigma_e$  finite set of (instantaneous) events
- ▶  $\Sigma_s$  finite set of signals
- ▶  $\mathbb{T}$  time domain,  $\overline{\mathbb{T}} = \mathbb{T} \cup \{\infty\}$
- ▶  $\Sigma = \Sigma_e \cup (\Sigma_s \times \mathbb{T})$
- ▶ Notation:  $a^d$  for  $(a, d) \in \Sigma_s \times \overline{\mathbb{T}}$
- ▶  $\Sigma^\infty$  : set of finite and infinite words over  $\Sigma$

## Signal stuttering

$$a^2 a^3 \approx a^5, \quad a^1 \approx a^{\frac{1}{2}} a^{\frac{1}{4}} a^{\frac{1}{8}} \dots, \quad a^\infty = a^2 a^2 a^2 \dots$$



Observation of signal  $a$  is not interrupted by an internal (instantaneous) action  $\varepsilon$

# Signal-Event (Timed) Words

## Unobservable signal $\tau$

- ▶ Useful to hide signals:

Signal-event word  $\xrightarrow{\text{hiding signals}}$  time-event word

$$a^3fb^1gfa^2f$$

$$\tau^3f\tau^1gf\tau^2f = (f, 3)(g, 4)(f, 4)(f, 6)$$

- ▶  $\tau^0 \approx \varepsilon$  : a hidden signal with zero duration is not observable.  
 $a^0 \not\approx \varepsilon$  : a signal, even of zero duration, is observable.  
 $\tau^2 \not\approx \varepsilon$  : we still observe a time delay but the actual signal has been hidden.  
Example :  $a^2\tau^0a^1f\tau^0g\tau^1fb^2b^2b^2 \dots \approx a^3fg\tau^1fb^\infty$
- ▶  $SE(\Sigma) = \Sigma^\infty / \approx$  : signal-event words
- ▶  $SEL_\varepsilon$  : languages accepted by  $SE$ -automata
- ▶  $SEL$  : languages accepted by  $SE$ -automata without  $\varepsilon$ -transitions

# Signal-Event (Timed) Words

## Unobservable signal $\tau$

- ▶ Useful to hide signals:

Signal-event word  $\xrightarrow{\text{hiding signals}}$  time-event word

$$a^3fb^1gfa^2f$$

$$\tau^3f\tau^1gf\tau^2f = (f, 3)(g, 4)(f, 4)(f, 6)$$

- ▶  $\tau^0 \approx \varepsilon$  : a hidden signal with zero duration is not observable.  
 $a^0 \not\approx \varepsilon$  : a signal, even of zero duration, is observable.  
 $\tau^2 \not\approx \varepsilon$  : we still observe a time delay but the actual signal has been hidden.  
Example :  $a^2\tau^0a^1f\tau^0g\tau^1fb^2b^2b^2 \dots \approx a^3fg\tau^1fb^\infty$

- ▶  $SE(\Sigma) = \Sigma^\infty / \approx$  : signal-event words
- ▶  $SEL_\varepsilon$  : languages accepted by  $SE$ -automata
- ▶  $SEL$  : languages accepted by  $SE$ -automata without  $\varepsilon$ -transitions

# Signal-Event (Timed) Words

## Unobservable signal $\tau$

- ▶ Useful to hide signals:

Signal-event word  $\xrightarrow{\text{hiding signals}}$  time-event word

$$a^3fb^1gfa^2f$$

$$\tau^3f\tau^1gf\tau^2f = (f, 3)(g, 4)(f, 4)(f, 6)$$

- ▶  $\tau^0 \approx \varepsilon$  : a hidden signal with zero duration is not observable.  
 $a^0 \not\approx \varepsilon$  : a signal, even of zero duration, is observable.  
 $\tau^2 \not\approx \varepsilon$  : we still observe a time delay but the actual signal has been hidden.  
Example :  $a^2\tau^0a^1f\tau^0g\tau^1fb^2b^2b^2 \dots \approx a^3fg\tau^1fb^\infty$
- ▶  $SE(\Sigma) = \Sigma^\infty / \approx$  : **signal-event words**
- ▶  $SEL_\varepsilon$  : languages accepted by  $SE$ -automata
- ▶  $SEL$  : languages accepted by  $SE$ -automata without  $\varepsilon$ -transitions

# Outline

Introduction

Signal-Event (Timed) Words and Automata

Closure under intersection

Conclusion

# Closure under intersection

## Theorem

Classes  $SEL$  and  $SEL_\varepsilon$  are closed under intersection

## Remarks

- Easy for the class  $SEL$  or for time-event languages.
- More difficult with signals and  $\varepsilon$ -transitions due to stuttering and unobservability of  $\tau^0$ .
- Asarin, Caspi and Maler 97 does not handle signal stuttering and considers finite runs only.  
Asarin, Caspi and Maler 02 deals with the intersection of time-event automata only.
- Dima 00 gives a construction to remove stuttering for automata with a single clock.
- Durand-Lose 04 gives a construction for intersection taking stuttering into account but restricted to finite runs and without zero-duration signals. His approach does not extend to infinite runs since it would introduce Zeno runs leading to transfinite problems.

# Closure under intersection

## Theorem

Classes  $SEL$  and  $SEL_\varepsilon$  are closed under intersection

## Remarks

- ▶ Easy for the class  $SEL$  or for time-event languages.
- ▶ More difficult with signals and  $\varepsilon$ -transitions due to stuttering and unobservability of  $\tau^0$ .
- ▶ Asarin, Caspi and Maler 97 does not handle signal stuttering and considers finite runs only.  
Asarin, Caspi and Maler 02 deals with the intersection of time-event automata only.
- ▶ Dima 00 gives a construction to remove stuttering for automata with a single clock.
- ▶ Durand-Lose 04 gives a construction for intersection taking stuttering into account but restricted to finite runs and without zero-duration signals.  
His approach does not extend to infinite runs since it would introduce Zeno runs leading to transfinite problems.

# Closure under intersection

## Theorem

Classes  $SEL$  and  $SEL_\varepsilon$  are closed under intersection

## Remarks

- ▶ Easy for the class  $SEL$  or for time-event languages.
- ▶ More difficult with signals and  $\varepsilon$ -transitions due to stuttering and unobservability of  $\tau^0$ .
- ▶ Asarin, Caspi and Maler 97 does not handle signal stuttering and considers finite runs only.  
Asarin, Caspi and Maler 02 deals with the intersection of time-event automata only.
- ▶ Dima 00 gives a construction to remove stuttering for automata with a single clock.
- ▶ Durand-Lose 04 gives a construction for intersection taking stuttering into account but restricted to finite runs and without zero-duration signals. His approach does not extend to infinite runs since it would introduce Zeno runs leading to transfinite problems.

# Closure under intersection

## Theorem

Classes  $SEL$  and  $SEL_\varepsilon$  are closed under intersection

## Remarks

- ▶ Easy for the class  $SEL$  or for time-event languages.
- ▶ More difficult with signals and  $\varepsilon$ -transitions due to stuttering and unobservability of  $\tau^0$ .
- ▶ Asarin, Caspi and Maler 97 does not handle signal stuttering and considers finite runs only.  
Asarin, Caspi and Maler 02 deals with the intersection of time-event automata only.
- ▶ Dima 00 gives a construction to remove stuttering for automata with a single clock.
- ▶ Durand-Lose 04 gives a construction for intersection taking stuttering into account but restricted to finite runs and without zero-duration signals. His approach does not extend to infinite runs since it would introduce Zeno runs leading to transfinite problems.

# Closure under intersection

## Theorem

Classes  $SEL$  and  $SEL_\varepsilon$  are closed under intersection

## Remarks

- ▶ Easy for the class  $SEL$  or for time-event languages.
- ▶ More difficult with signals and  $\varepsilon$ -transitions due to stuttering and unobservability of  $\tau^0$ .
- ▶ Asarin, Caspi and Maler 97 does not handle signal stuttering and considers finite runs only.  
Asarin, Caspi and Maler 02 deals with the intersection of time-event automata only.
- ▶ Dima 00 gives a construction to remove stuttering for automata with a single clock.
- ▶ Durand-Lose 04 gives a construction for intersection taking stuttering into account but restricted to finite runs and without zero-duration signals. His approach does not extend to infinite runs since it would introduce Zeno runs leading to transfinite problems.

# Closure under intersection

## Theorem

Classes  $SEL$  and  $SEL_\varepsilon$  are closed under intersection

## Remarks

- ▶ Easy for the class  $SEL$  or for time-event languages.
- ▶ More difficult with signals and  $\varepsilon$ -transitions due to stuttering and unobservability of  $\tau^0$ .
- ▶ Asarin, Caspi and Maler 97 does not handle signal stuttering and considers finite runs only.  
Asarin, Caspi and Maler 02 deals with the intersection of time-event automata only.
- ▶ Dima 00 gives a construction to remove stuttering for automata with a single clock.
- ▶ Durand-Lose 04 gives a construction for intersection taking stuttering into account but restricted to finite runs and without zero-duration signals. His approach does not extend to infinite runs since it would introduce Zeno runs leading to transfinite problems.

# Closure under intersection

## Theorem

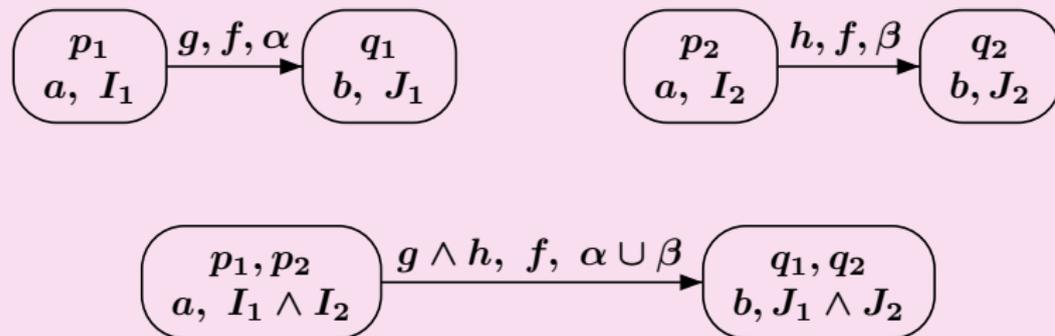
Classes  $SEL$  and  $SEL_\epsilon$  are closed under intersection

# Closure under intersection

## Theorem

Classes  $SEL$  and  $SEL_\epsilon$  are closed under intersection

Basic technique for  $SEL$  or time-event words

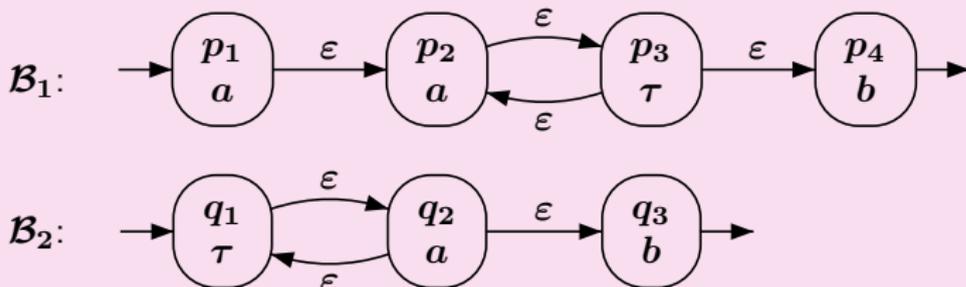


# Closure under intersection

## Theorem

$SEL_\epsilon$  is closed under intersection

Problem 1 : stuttering with unobservability of  $\tau^0$

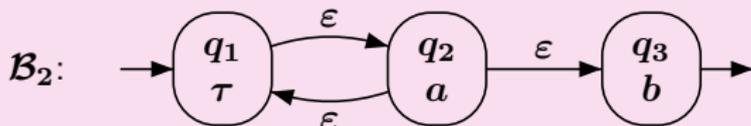
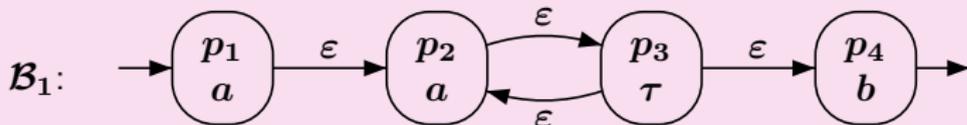


# Closure under intersection

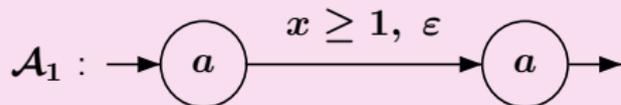
## Theorem

$SEL_\epsilon$  is closed under intersection

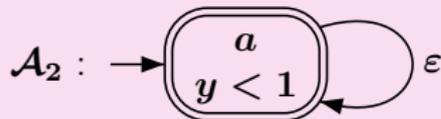
Problem 1 : stuttering with unobservability of  $\tau^0$



Problem 2 : finite and infinite runs



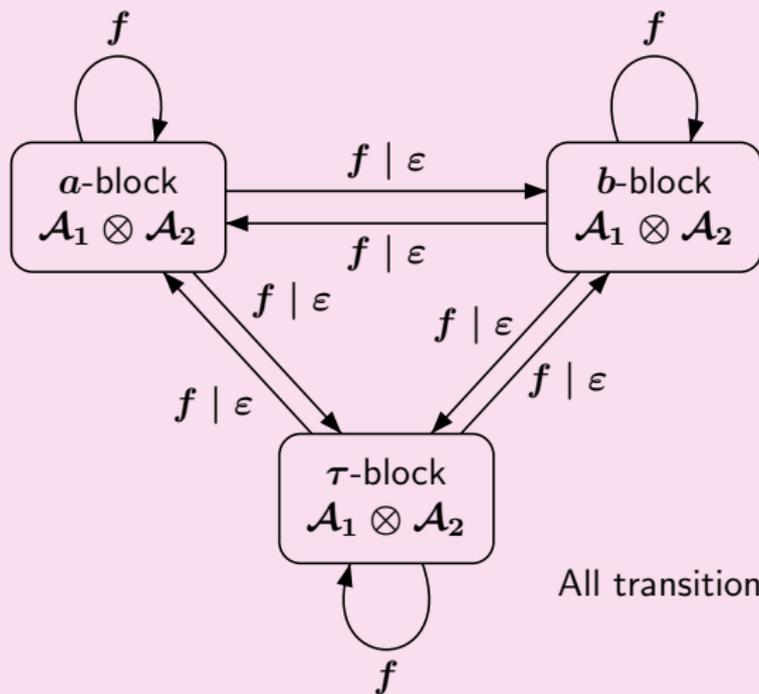
$$\mathcal{L}(\mathcal{A}_1) \cap \mathcal{L}(\mathcal{A}_2) = \{a^1\}$$



$$a^1 \approx a^{\frac{1}{2}} a^{\frac{1}{4}} a^{\frac{1}{8}} \dots$$

# Stuttering with unobservability of $\tau^0$

Connecting modules for  $a$ -blocks with synchronous transitions

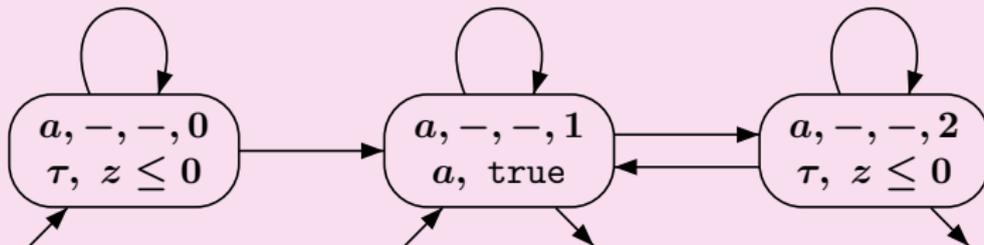


All transitions reset a new clock  $z$

# Stuttering with unobservability of $\tau^0$

## Building maximal $a$ -blocks

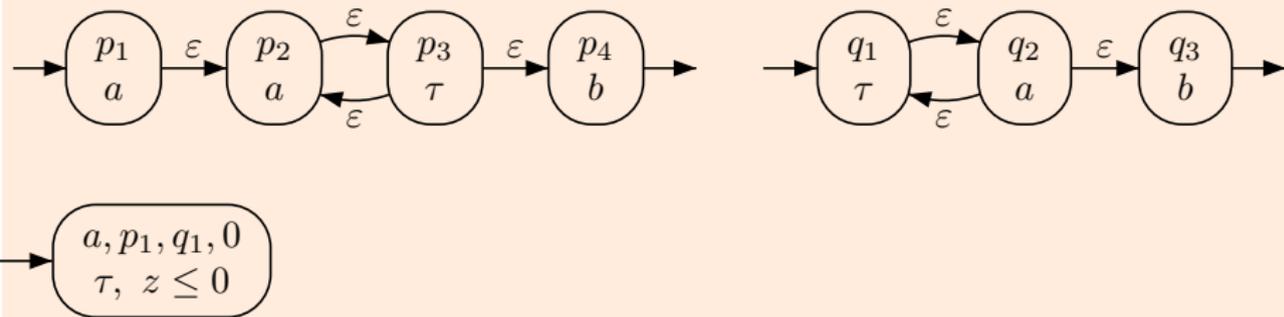
States :  $(a, p, q, i)$ , where  $i$  is the synchronization mode.



with  $a \neq \tau$  and asynchronous  $\varepsilon$ -transitions that reset clock  $z$ .

# Example

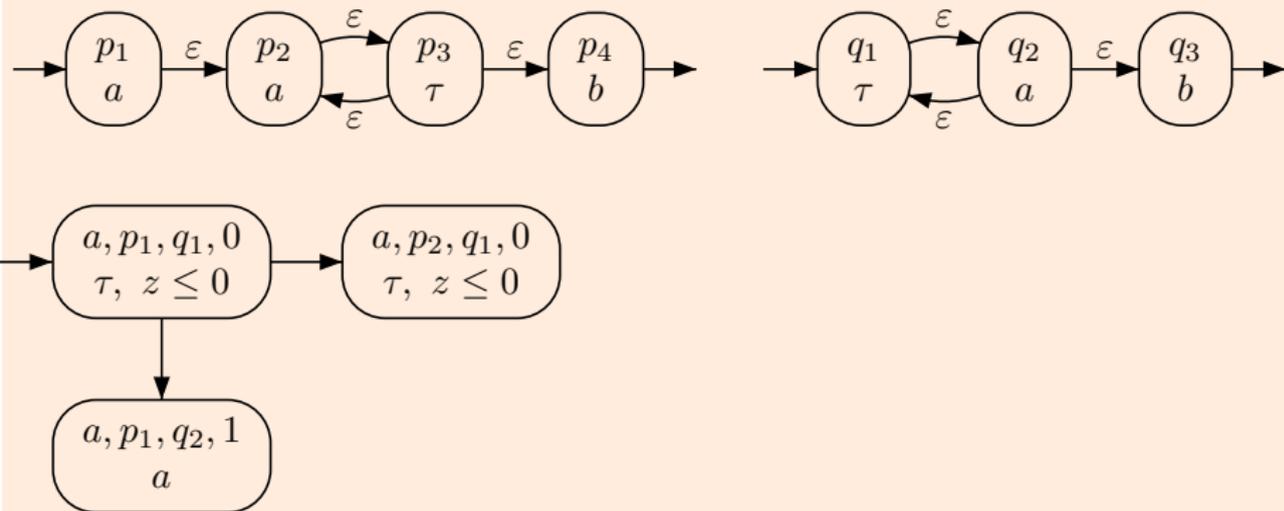
The  $a$ -block for  $\mathcal{B}_1$  and  $\mathcal{B}_2$



To be completed with a  $\tau$ -block and a  $b$ -block.

# Example

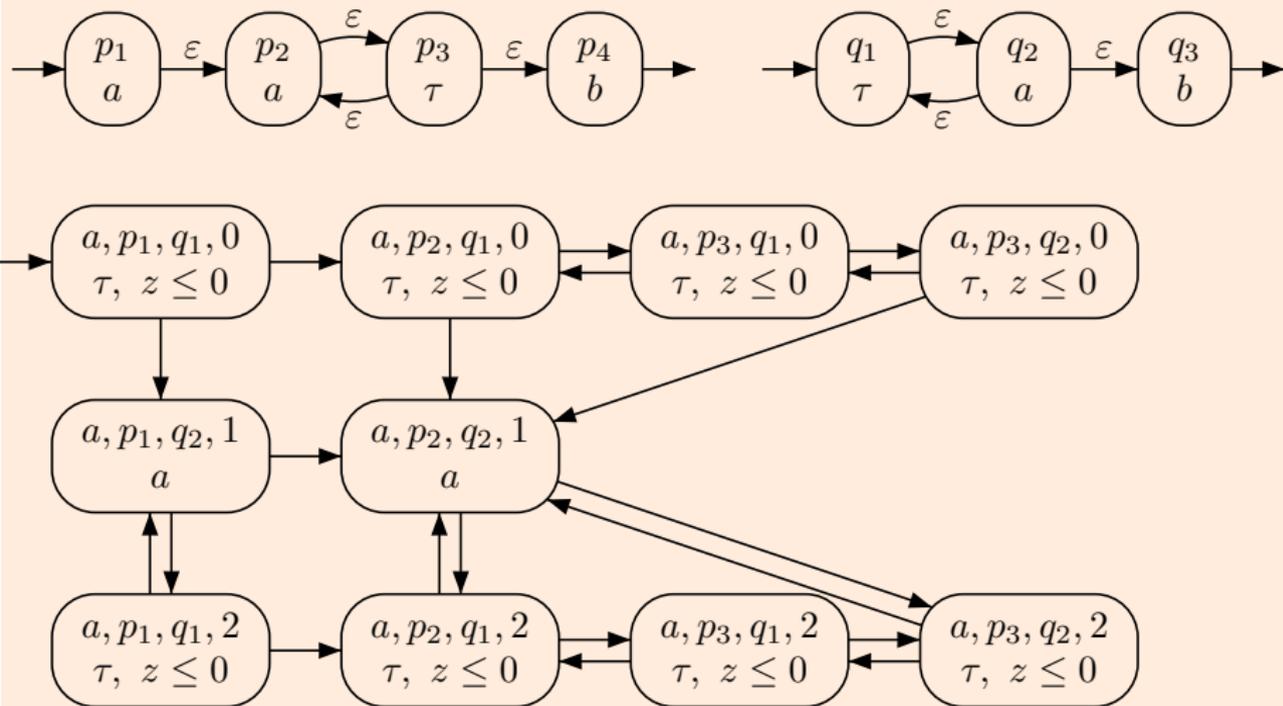
The  $a$ -block for  $\mathcal{B}_1$  and  $\mathcal{B}_2$



To be completed with a  $\tau$ -block and a  $b$ -block.

# Example

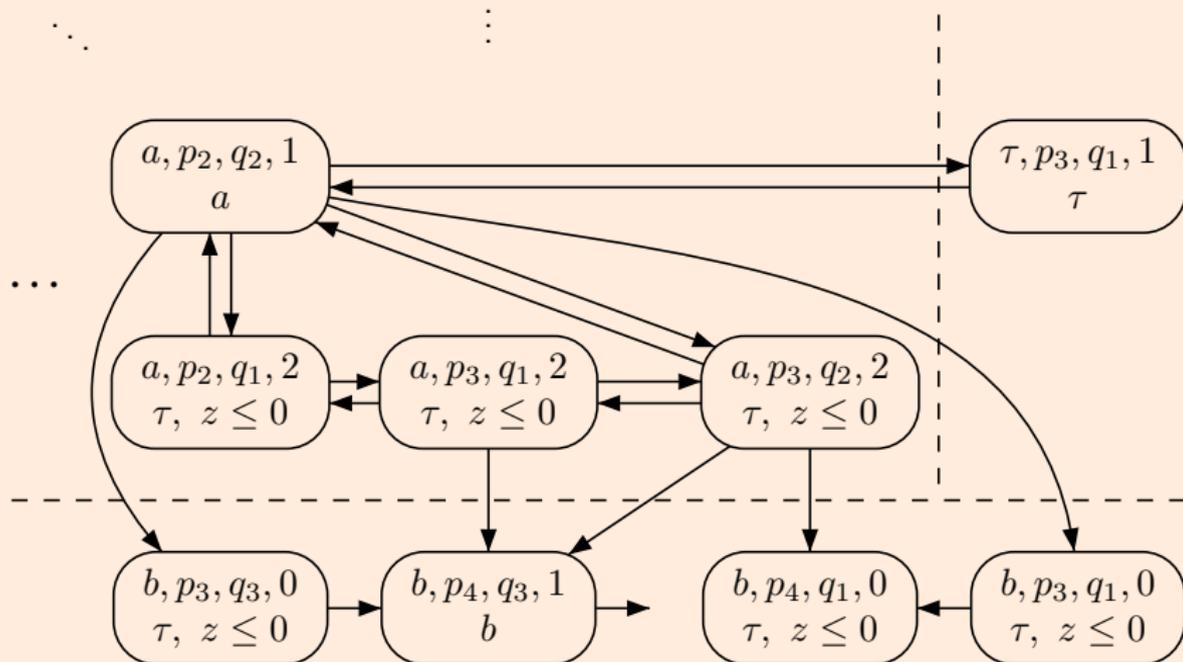
The  $a$ -block for  $\mathcal{B}_1$  and  $\mathcal{B}_2$



To be completed with a  $\tau$ -block and a  $b$ -block.

# Example (cont.)

## Connecting the blocks



# Finite and infinite runs

## Theorem : a normal form for SE-automata

Let  $\mathcal{A}$  be a SE-automaton. We can effectively construct an equivalent SE-automaton  $\mathcal{A}'$  such that:

1. no infinite run of  $\mathcal{A}'$  accepts a finite word with finite duration, and
2. no finite run of  $\mathcal{A}'$  accepts a word with infinite duration.

## Remarks

- ▶ The construction removes Zeno runs accepting finite runs with finite duration: replacing for instance an infinite  $\varepsilon$ -loop producing  $a^{\frac{1}{2}}, a^{\frac{1}{4}}, a^{\frac{1}{8}} \dots$  by a finite run producing  $a^1$ .
- ▶ Easy if Zeno runs or  $\varepsilon$ -transitions are forbidden.
- ▶ The result is interesting in itself to obtain a more realistic implementation of an arbitrary SE-automaton.

# Finite and infinite runs

## Theorem : a normal form for SE-automata

Let  $\mathcal{A}$  be a SE-automaton. We can effectively construct an equivalent SE-automaton  $\mathcal{A}'$  such that:

1. no infinite run of  $\mathcal{A}'$  accepts a finite word with finite duration, and
2. no finite run of  $\mathcal{A}'$  accepts a word with infinite duration.

## Remarks

- ▶ The construction removes Zeno runs accepting finite runs with finite duration: replacing for instance an infinite  $\varepsilon$ -loop producing  $a^{\frac{1}{2}}, a^{\frac{1}{4}}, a^{\frac{1}{8}} \dots$  by a finite run producing  $a^1$ .
- ▶ Easy if Zeno runs or  $\varepsilon$ -transitions are forbidden.
- ▶ The result is interesting in itself to obtain a more realistic implementation of an arbitrary SE-automaton.

# Finite and infinite runs

## Theorem : a normal form for SE-automata

Let  $\mathcal{A}$  be a SE-automaton. We can effectively construct an equivalent SE-automaton  $\mathcal{A}'$  such that:

1. no infinite run of  $\mathcal{A}'$  accepts a finite word with finite duration, and
2. no finite run of  $\mathcal{A}'$  accepts a word with infinite duration.

## Remarks

- ▶ The construction removes Zeno runs accepting finite runs with finite duration: replacing for instance an infinite  $\varepsilon$ -loop producing  $a^{\frac{1}{2}}, a^{\frac{1}{4}}, a^{\frac{1}{8}} \dots$  by a finite run producing  $a^1$ .
- ▶ Easy if Zeno runs or  $\varepsilon$ -transitions are forbidden.
- ▶ The result is interesting in itself to obtain a more realistic implementation of an arbitrary SE-automaton.

# Finite and infinite runs

## Theorem : a normal form for SE-automata

Let  $\mathcal{A}$  be a SE-automaton. We can effectively construct an equivalent SE-automaton  $\mathcal{A}'$  such that:

1. no infinite run of  $\mathcal{A}'$  accepts a finite word with finite duration, and
2. no finite run of  $\mathcal{A}'$  accepts a word with infinite duration.

## Remarks

- ▶ The construction removes Zeno runs accepting finite runs with finite duration: replacing for instance an infinite  $\varepsilon$ -loop producing  $a^{\frac{1}{2}}, a^{\frac{1}{4}}, a^{\frac{1}{8}} \dots$  by a finite run producing  $a^1$ .
- ▶ Easy if Zeno runs or  $\varepsilon$ -transitions are forbidden.
- ▶ The result is interesting in itself to obtain a more realistic implementation of an arbitrary SE-automaton.

# Finite and infinite runs

## Theorem: a normal form for SE-automata

Let  $\mathcal{A}$  be a SE-automaton. We can effectively construct an equivalent SE-automaton  $\mathcal{A}'$  such that:

1. no infinite run of  $\mathcal{A}'$  accepts a finite word with finite duration, and
2. no finite run of  $\mathcal{A}'$  accepts a word with infinite duration.

## Main problem

We have to replace **infinite accepting  $\varepsilon$ -loops**

by **finite accepting runs**.

# Finite and infinite runs

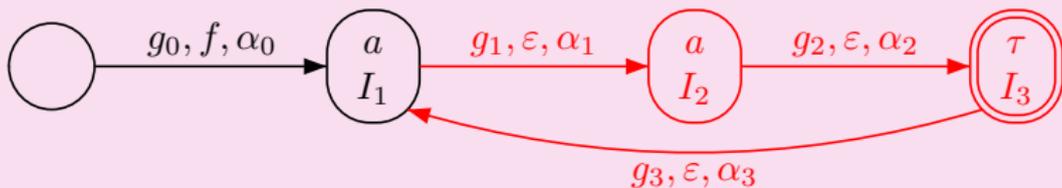
Theorem: a normal form for SE-automata

Let  $\mathcal{A}$  be a SE-automaton. We can effectively construct an equivalent SE-automaton  $\mathcal{A}'$  such that:

1. no infinite run of  $\mathcal{A}'$  accepts a finite word with finite duration, and
2. no finite run of  $\mathcal{A}'$  accepts a word with infinite duration.

Main problem

We have to replace **infinite accepting  $\varepsilon$ -loops**



by **finite accepting runs**.

# Finite and infinite runs

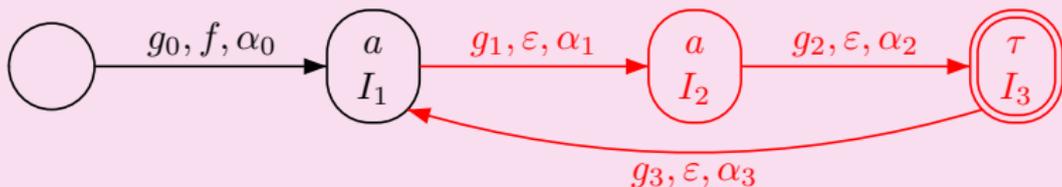
Theorem: a normal form for SE-automata

Let  $\mathcal{A}$  be a SE-automaton. We can effectively construct an equivalent SE-automaton  $\mathcal{A}'$  such that:

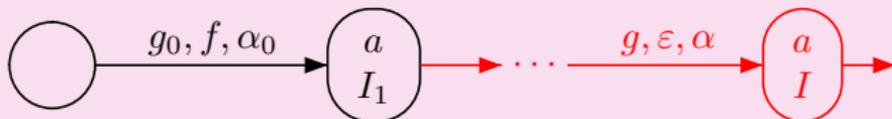
1. no infinite run of  $\mathcal{A}'$  accepts a finite word with finite duration, and
2. no finite run of  $\mathcal{A}'$  accepts a word with infinite duration.

## Main problem

We have to replace **infinite accepting  $\varepsilon$ -loops**

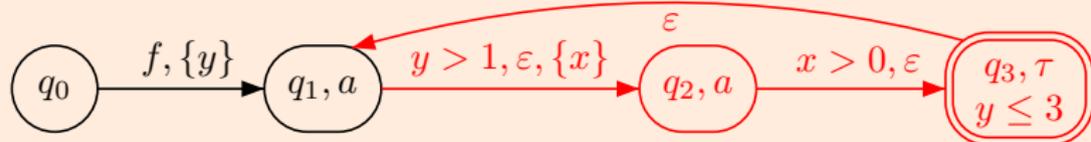


by **finite accepting runs**.



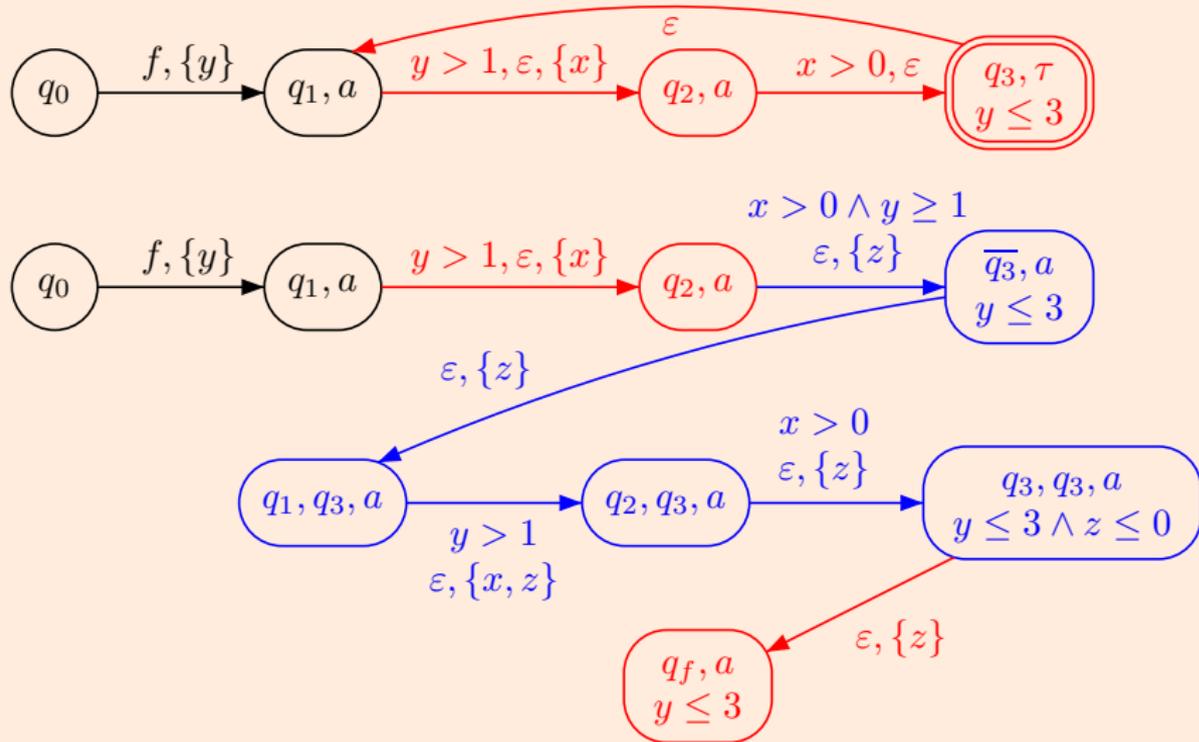
# Example

## Simulating the loop



# Example

## Simulating the loop



# Outline

Introduction

Signal-Event (Timed) Words and Automata

Closure under intersection

Conclusion

# Conclusion

- ▶ Extending classical results to SE-automata is not always easy due to  $\varepsilon$ -transitions, signal stuttering, unobservability of  $\tau^0$ , Zeno runs, ...
- ▶ We have proved closure under intersection for the general case of languages accepted by SE-automata.
- ▶ Signal-event words are natural objects for studying refinements and abstractions, see next talk.