

# Static analysis of **run-time errors** in programs with **floating-point** computations

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# The cost of software failure

- **Patriot MIM-104** failure, 25 February 1991  
(death of 28 soldiers<sup>1</sup>)
- **Ariane 5** failure, 4 June 1996  
(cost estimated at more than 370 000 000 US\$<sup>2</sup>)
- **Toyota** electronic throttle control system failure, 2005  
(at least 89 death<sup>3</sup>)
- **Heartbleed** bug in OpenSSL, April 2014
- **Stagefright** bug in Android, Summer 2015  
(multiple array overflows in 900 million devices, some exploitable)
- economic cost of software bugs is tremendous<sup>4</sup>

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<sup>1</sup>R. Skeel. "Roundoff Error and the Patriot Missile". *SIAM News*, volume 25, nr 4.

<sup>2</sup>M. Dowson. "The Ariane 5 Software Failure". *Software Engineering Notes* 22 (2): 84, March 1997.

<sup>3</sup>CBSNews. Toyota "Unintended Acceleration" Has Killed 89. 20 March 2014.

<sup>4</sup>NIST. Software errors cost U.S. economy \$59.5 billion annually. Tech. report, NIST Planning Report, 2002.

# Static analysis

Goal: static analysis [CousotCousot-ISP76]

**Static** (automatic) discovery  
of **dynamic** (semantic) properties of programs.

## Applications:

- compilation and optimisation, e.g.:
  - array bound check elimination
  - alias analysis
- verification, e.g.:
  - infer invariants
  - prove the absence of run-time errors  
(division by zero, overflow, invalid array access)
  - prove functional properties

We focus here on numerical properties of numerical variables.

# Example analysis: inferring numeric invariants

## Insertion Sort

```
for i=1 to 99 do

  p := T[i]; j := i+1;

  while j <= 100 and T[j] < p do

    T[j-1] := T[j]; j := j+1;

  end;

  T[j-1] := p;
end;
```

# Example analysis: inferring numeric invariants

Interval analysis:

## Insertion Sort

```
for i=1 to 99 do
   $i \in [1, 99]$ 
  p := T[i]; j := i+1;
   $i \in [1, 99], j \in [2, 100]$ 
  while j <= 100 and T[j] < p do
     $i \in [1, 99], j \in [2, 100]$ 
    T[j-1] := T[j]; j := j+1;
     $i \in [1, 99], j \in [3, 101]$ 
  end;
   $i \in [1, 99], j \in [2, 101]$ 
  T[j-1] := p;
end;
```

⇒ there is no out of bound array access

# Example analysis: inferring numeric invariants

Linear inequality analysis:

## Insertion Sort

```
for i=1 to 99 do
   $i \in [1, 99]$ 
  p := T[i]; j := i+1;
   $i \in [1, 99], j = i + 1$ 
  while j <= 100 and T[j] < p do
     $i \in [1, 99], i + 1 \leq j \leq 100$ 
    T[j-1] := T[j]; j := j+1;
     $i \in [1, 99], i + 2 \leq j \leq 101$ 
  end;
   $i \in [1, 99], i + 1 \leq j \leq 101$ 
  T[j-1] := p;
end;
```

# Theoretical background

**Abstract interpretation**: unifying theory of program semantics

[CousotCousot-POPL77]

Provide theoretical tools to design and compare static analyses that:

- always terminate
- are approximate (solve undecidability and efficiency issues)
- are sound by construction (no behavior is omitted)

Analysis design roadmap:

- 1 concrete semantics
- 2 abstract domains

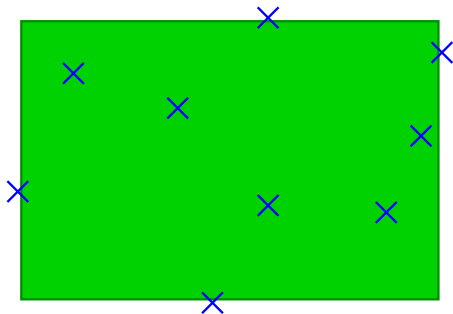
# Abstract domain examples



concrete  $\mathcal{D}$  :  $\{(0, 3), (5.5, 0), (12, 7), \dots\}$  (not computable)

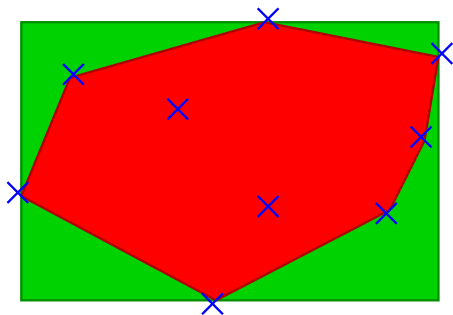


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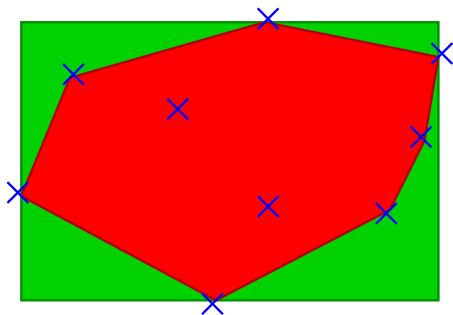


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polyhedra  $\mathcal{D}_p^\#$  :  $6X + 11Y \geq 33 \wedge \dots$  (exponential cost)

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$\implies$  trade-off cost vs. precision and expressiveness.

# Overview

- **Classic domains** (on rationals)
  - concrete semantics
  - interval domain
  - polyhedra domain
- **Floating-point domains**
  - concrete semantics of floats
  - floats intervals
  - linearization of float expressions
  - **Application:** the Astrée analyzer
  - float polyhedra

# Classic Domains

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# Toy language: syntax

## arithmetic expressions:

<code>exp</code>	<code>::=</code>	<code>V</code>	variable $V \in \mathcal{V}$
		<code>-exp</code>	negation
		<code>exp <math>\diamond</math> exp</code>	binary operation: $\diamond \in \{+, -, \times, /\}$
		<code>[c, c']</code>	constant range, $c, c' \in \mathbb{Q} \cup \{\pm\infty\}$ ( <code>c</code> is a shorthand for <code>[c, c]</code> )

## programs:

<code>prog</code>	<code>::=</code>	<code>V := exp</code>	assignment
		<code>if exp <math>\bowtie</math> 0 then prog else prog fi</code>	test
		<code>while exp <math>\bowtie</math> 0 do prog done</code>	loop
		<code>prog; prog</code>	sequence

Finite set  $\mathcal{V}$  of variables, with value in  $\mathbb{Q}$   
 (later extended to floats  $\mathbb{F}$  and machine integers  $\mathbb{M}$ )

# Concrete semantics

Semantics of expressions:  $E[e]: (\mathcal{V} \rightarrow \mathbb{Q}) \rightarrow \mathcal{P}(\mathbb{Q})$

The evaluation of  $e$  in  $\rho$  gives a **set** of values:

$$\begin{aligned}
 E[[c, c']] \rho &\stackrel{\text{def}}{=} \{x \in \mathbb{Q} \mid c \leq x \leq c'\} \\
 E[[V]] \rho &\stackrel{\text{def}}{=} \{\rho(V)\} \\
 E[[-e]] \rho &\stackrel{\text{def}}{=} \{-v \mid v \in E[e] \rho\} \\
 E[[e_1 + e_2]] \rho &\stackrel{\text{def}}{=} \{v_1 + v_2 \mid v_1 \in E[[e_1]] \rho, v_2 \in E[[e_2]] \rho\} \\
 E[[e_1 - e_2]] \rho &\stackrel{\text{def}}{=} \{v_1 - v_2 \mid v_1 \in E[[e_1]] \rho, v_2 \in E[[e_2]] \rho\} \\
 E[[e_1 \times e_2]] \rho &\stackrel{\text{def}}{=} \{v_1 \times v_2 \mid v_1 \in E[[e_1]] \rho, v_2 \in E[[e_2]] \rho\} \\
 E[[e_1 / e_2]] \rho &\stackrel{\text{def}}{=} \{v_1 / v_2 \mid v_1 \in E[[e_1]] \rho, v_2 \in E[[e_2]] \rho, v_2 \neq 0\}
 \end{aligned}$$

# Concrete semantics

Semantics of programs:  $C[[p]]: \mathcal{D} \rightarrow \mathcal{D}$

where  $\mathcal{D} \stackrel{\text{def}}{=} \mathcal{P}(\mathcal{V} \rightarrow \mathbb{Q})$

A **transfer function** for  $p$  defines a **relation** on environments  $\rho \in \mathcal{D}$ :

$$C[[v := e]] \mathcal{X} \stackrel{\text{def}}{=} \{ \rho[v \mapsto v] \mid \rho \in \mathcal{X}, v \in E[[e]] \rho \}$$

$$C[[e \bowtie 0]] \mathcal{X} \stackrel{\text{def}}{=} \{ \rho \mid \rho \in \mathcal{X}, \exists v \in E[[e]] \rho, v \bowtie 0 \}$$

$$C[[b_1; b_2]] \mathcal{X} \stackrel{\text{def}}{=} C[[b_2]](C[[b_1]] \mathcal{X})$$

$$C[[\text{if } e \bowtie 0 \text{ then } b_1 \text{ else } b_2]] \mathcal{X} \stackrel{\text{def}}{=} \\ (C[[b_1]] \circ C[[e \bowtie 0]]) \mathcal{X} \cup (C[[b_2]] \circ C[[e \nabla 0]]) \mathcal{X}$$

$$C[[\text{while } e \bowtie 0 \text{ do } b \text{ done}]] \mathcal{X} \stackrel{\text{def}}{=} \\ C[[e \nabla 0]](\text{lfp } \lambda \mathcal{Y}. \mathcal{X} \cup (C[[b]] \circ C[[e \bowtie 0]]) \mathcal{Y})$$

It relates the environments after the execution of a command to the environments before.



# Abstract domains

- Abstract elements:
  - $\mathcal{D}^\#$  set of computer-representable elements
  - $\gamma : \mathcal{D}^\# \rightarrow \mathcal{D}$  concretization
  - $\subseteq^\#$  approximation order:  $\mathcal{X}^\# \subseteq^\# \mathcal{Y}^\# \implies \gamma(\mathcal{X}^\#) \subseteq \gamma(\mathcal{Y}^\#)$
- Abstract operators:
  - $C^\#[[c]] : \mathcal{D}^\# \rightarrow \mathcal{D}^\#$  and  $U^\# : (\mathcal{D}^\# \times \mathcal{D}^\#) \rightarrow \mathcal{D}^\#$
  - soundness:  $F \circ \gamma \subseteq \gamma \circ F^\#$
- Fixpoint extrapolation
  - $\nabla : (\mathcal{D}^\# \times \mathcal{D}^\#) \rightarrow \mathcal{D}^\#$  widening
  - soundness:  $\gamma(\mathcal{X}^\#) \cup \gamma(\mathcal{Y}^\#) \subseteq \gamma(\mathcal{X}^\# \nabla \mathcal{Y}^\#)$
  - termination:  $\forall$  sequence  $(\mathcal{Y}_i^\#)_{i \in \mathbb{N}}$   
 the sequence  $\mathcal{X}_0^\# = \mathcal{Y}_0^\#, \mathcal{X}_{i+1}^\# = \mathcal{X}_i^\# \nabla \mathcal{Y}_{i+1}^\#$   
 stabilizes in finite time:  $\exists n < \omega, \mathcal{X}_{n+1}^\# = \mathcal{X}_n^\#$

Both **semantics** and **algorithmic** aspects.

# Abstract semantics

Given by the abstract domain:

- sound  $C^\# \llbracket v := e \rrbracket, C^\# \llbracket e \bowtie 0 \rrbracket, \cup^\#$
- sound and terminating  $\nabla$

Derived analysis: from the concrete...

$$C \llbracket b_1; b_2 \rrbracket \mathcal{X} \stackrel{\text{def}}{=} C \llbracket b_2 \rrbracket (C \llbracket b_1 \rrbracket \mathcal{X})$$

$$C \llbracket \text{if } e \bowtie 0 \text{ then } b_1 \text{ else } b_2 \rrbracket \mathcal{X} \stackrel{\text{def}}{=} \\ (C \llbracket b_1 \rrbracket \circ C \llbracket e \bowtie 0 \rrbracket) \mathcal{X} \cup (C \llbracket b_2 \rrbracket \circ C \llbracket e \nabla 0 \rrbracket) \mathcal{X}$$

$$C \llbracket \text{while } e \bowtie 0 \text{ do } b \text{ done} \rrbracket \mathcal{X} \stackrel{\text{def}}{=} \\ C \llbracket e \nabla 0 \rrbracket (\text{lfp } \lambda \mathcal{Y}. \mathcal{X} \cup (C \llbracket b \rrbracket \circ C \llbracket e \bowtie 0 \rrbracket) \mathcal{Y})$$

# Abstract semantics

Given by the abstract domain:

- sound  $C^\# \llbracket v := e \rrbracket, C^\# \llbracket e \bowtie 0 \rrbracket, \cup^\#$
- sound and terminating  $\nabla$

Derived analysis: ... to the abstract

$$C^\# \llbracket b_1; b_2 \rrbracket \mathcal{X}^\# \stackrel{\text{def}}{=} C^\# \llbracket b_2 \rrbracket (C^\# \llbracket b_1 \rrbracket \mathcal{X}^\#)$$

$$C^\# \llbracket \text{if } e \bowtie 0 \text{ then } b_1 \text{ else } b_2 \rrbracket \mathcal{X}^\# \stackrel{\text{def}}{=} \\ (C^\# \llbracket b_1 \rrbracket \circ C^\# \llbracket e \bowtie 0 \rrbracket) \mathcal{X}^\# \cup^\# (C^\# \llbracket b_2 \rrbracket \circ C^\# \llbracket e \not\bowtie 0 \rrbracket) \mathcal{X}^\#$$

$$C^\# \llbracket \text{while } e \bowtie 0 \text{ do } b \text{ done} \rrbracket \mathcal{X}^\# \stackrel{\text{def}}{=} \\ C^\# \llbracket e \not\bowtie 0 \rrbracket (\lim \lambda \mathcal{Y}^\#. \mathcal{Y}^\# \nabla (\mathcal{X}^\# \cup^\# (C^\# \llbracket b \rrbracket \circ C^\# \llbracket e \bowtie 0 \rrbracket) \mathcal{Y}^\#))$$

The derived analysis is sound and terminates.

# Interval domain

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# Interval lattice

$$\mathcal{B}^\# \stackrel{\text{def}}{=} \{[a, b] \mid a \in \mathbb{Q} \cup \{-\infty\}, b \in \mathbb{Q} \cup \{+\infty\}, a \leq b\}$$

[Cousot 76]

**Galois connection:**  $\mathcal{P}(\mathbb{Q}) \begin{matrix} \xleftarrow{\gamma_b} \\ \xrightarrow{\alpha_b} \end{matrix} \mathcal{B}^\# \cup \{\perp^\#\}$

$$\gamma([a, b]) \stackrel{\text{def}}{=} \{x \in \mathbb{Q} \mid a \leq x \leq b\}$$

$$\alpha(\mathcal{X}) \stackrel{\text{def}}{=} \begin{cases} \perp^\# & \text{if } \mathcal{X} = \emptyset \\ [\min \mathcal{X}, \max \mathcal{X}] & \text{otherwise} \end{cases}$$

**Partial order:**

$$[a, b] \stackrel{\text{def}}{\subseteq^\#} [c, d] \iff a \geq c \text{ and } b \leq d$$

$$\top^\# \stackrel{\text{def}}{=} ] - \infty, +\infty [$$

$$[a, b] \stackrel{\text{def}}{\cup^\#} [c, d] \iff [\min(a, c), \max(b, d)]$$

$$[a, b] \stackrel{\text{def}}{\cap^\#} [c, d] \iff \begin{cases} [\max(a, c), \min(b, d)] & \text{if } \max \leq \min \\ \perp^\# & \text{otherwise} \end{cases}$$

# Interval abstract arithmetic operators

Based on **interval arithmetic** [Moore 66]

$$[c, c']^{\#} \stackrel{\text{def}}{=} [c, c']$$

$$-^{\#} [a, b] \stackrel{\text{def}}{=} [-b, -a]$$

$$[a, b] +^{\#} [c, d] \stackrel{\text{def}}{=} [a + c, b + d]$$

$$[a, b] -^{\#} [c, d] \stackrel{\text{def}}{=} [a - d, b - c]$$

$$[a, b] \times^{\#} [c, d] \stackrel{\text{def}}{=} [\min(ac, ad, bc, bd), \max(ac, ad, bc, bd)]$$

$$[a, b] /^{\#} [c, d] \stackrel{\text{def}}{=} \dots$$

where  $\pm\infty \times 0 = 0$ .

# Interval abstract assignment

**Abstract evaluation of expressions:**  $E^\# \llbracket e \rrbracket : \mathcal{D}^\# \rightarrow \mathcal{B}^\#$

$$\begin{aligned}
 E^\# \llbracket [c, c'] \rrbracket \mathcal{X}^\# &\stackrel{\text{def}}{=} [c, c']^\# \\
 E^\# \llbracket v \rrbracket \mathcal{X}^\# &\stackrel{\text{def}}{=} \mathcal{X}^\#(v) \\
 E^\# \llbracket -e \rrbracket \mathcal{X}^\# &\stackrel{\text{def}}{=} -^\# E^\# \llbracket e \rrbracket \mathcal{X}^\# \\
 E^\# \llbracket e_1 \diamond e_2 \rrbracket \mathcal{X}^\# &\stackrel{\text{def}}{=} E^\# \llbracket e_1 \rrbracket \mathcal{X}^\# \diamond^\# E^\# \llbracket e_2 \rrbracket \mathcal{X}^\#
 \end{aligned}$$

**Abstract assignment:**

$$C^\# \llbracket v := e \rrbracket \mathcal{X}^\# \stackrel{\text{def}}{=} \begin{cases} \perp^\# & \text{if } \mathcal{V}^\# = \perp^\# \\ \mathcal{X}^\# [v \mapsto \mathcal{V}^\#] & \text{otherwise} \end{cases}$$

where  $\mathcal{V}^\# = E^\# \llbracket e \rrbracket \mathcal{X}^\#$ .

## Interval abstract tests

If  $\mathcal{X}^\sharp(X) = [a, b]$  and  $\mathcal{X}^\sharp(Y) = [c, d]$ , we can define:

$$C^\sharp[\![X - c \leq 0]\!] \mathcal{X}^\sharp \stackrel{\text{def}}{=} \begin{cases} \perp^\sharp & \text{if } a > c \\ \mathcal{X}^\sharp[X \mapsto [a, \min(b, c)]] & \text{otherwise} \end{cases}$$

$$C^\sharp[\![X - Y \leq 0]\!] \mathcal{X}^\sharp \stackrel{\text{def}}{=} \begin{cases} \perp^\sharp & \text{if } a > d \\ \mathcal{X}^\sharp[X \mapsto [a, \min(b, d)], \\ Y \mapsto [\max(c, a), d]] & \text{otherwise} \end{cases}$$

General case: constraint programming (HC4)



# Interval widening

## Interval widening example:

$$\perp^\# \quad \nabla \quad X^\# \quad \stackrel{\text{def}}{=} \quad X^\#$$

$$[a, b] \quad \nabla \quad [c, d] \quad \stackrel{\text{def}}{=} \quad \left[ \begin{cases} a & \text{if } a \leq c \\ -\infty & \text{otherwise} \end{cases}, \begin{cases} b & \text{if } b \geq d \\ +\infty & \text{otherwise} \end{cases} \right]$$

Unstable bounds are set to  $\pm\infty$

Smarter widenings also exist...

# Analysis with widening example

```
X:=0;  
while • X<40 do  
  X:=X+3  
done
```

# Analysis with widening example

```

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done

```

We must compute:

$$C^\# \llbracket X \geq 40 \rrbracket (\lim \lambda \mathcal{Y}^\# . \mathcal{Y}^\# \nabla (\mathcal{X}^\# \cup^\# C^\# \llbracket X := X+3 \rrbracket (C^\# \llbracket X < 40 \rrbracket \mathcal{Y}^\#)))$$

- $\mathcal{Y}_0^\# = \mathcal{X}^\# = [0, 0]$
- $\mathcal{Y}_1^\# = \mathcal{Y}_0^\# \nabla (\mathcal{X}^\# \cup^\# (\mathcal{Y}_0^\# +^\# [3, 3])) = [0, 0] \nabla ([0, 0] \cup^\# [3, 3]) = [0, +\infty]$
- $\mathcal{Y}_2^\# = \mathcal{Y}_1^\# \nabla (\mathcal{X}^\# \cup^\# (\mathcal{Y}_1^\# +^\# [3, 3])) = [0, +\infty] \nabla ([0, 0] \cup^\# [3, 42]) = \mathcal{Y}_1^\#$
- $C^\# \llbracket X \geq 40 \rrbracket (\mathcal{Y}_2^\#) = [42, +\infty]$

Decreasing iterations: to improve the precision

- after stabilization, continue iterating without  $\nabla$  (use  $\cap$ )
- in our case,  $\mathcal{Y}_3^\# = [0, 42]$ , so  $C^\# \llbracket X \geq 40 \rrbracket (\mathcal{Y}_3^\#) = [40, 42]$

# Polyhedra Domain

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# The need for relational domains

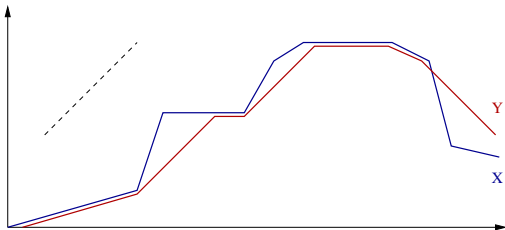
Non-relation domains cannot represent variable **relationships**

## Rate limiter

```

Y:=0; while • true do
  X:=[-128,128]; D:=[0,16];
  S:=Y; Y:=X; R:=X-S;
  if R<=-D then Y:=S-D fi;
  if R>=D then Y:=S+D fi
done
  
```

X: input signal  
 Y: output signal  
 S: last output  
 R: delta Y-S  
 D: max. allowed for |R|



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Iterations in the interval domain (without widening):

$x^{\#0}$	$x^{\#1}$	$x^{\#2}$	...	$x^{\#n}$
$Y = 0$	$ Y  \leq 144$	$ Y  \leq 160$	...	$ Y  \leq 128 + 16n$

In fact,  $Y \in [-128, 128]$  always holds.

To prove that, e.g.  $Y \geq -128$ , we must be able to:

- **represent** the properties  $R = X - S$  and  $R \leq -D$
- **combine** them to deduce  $S - X \geq D$ , and then  $Y = S - D \geq X$

# Polyhedra domain

Domain proposed by [Cousot Halbwachs 78]  
to infer conjunctions of affine inequalities  $\bigwedge_j (\sum_{i=1}^n \alpha_{ij} v_i \geq \beta_j)$ .

## Abstract elements:

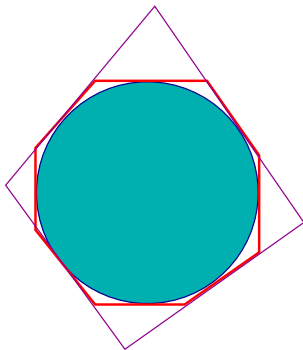
- $LinCons \stackrel{\text{def}}{=} \text{affine constraints over } \mathcal{V} \text{ with coefficients in } \mathbb{Q}$
- $\mathcal{D}^\# \stackrel{\text{def}}{=} \mathcal{P}_{\text{finite}}(LinCons)$

## Concretization:

$$\gamma(\mathcal{X}^\#) \stackrel{\text{def}}{=} \{ \rho \in \mathcal{V} \rightarrow \mathbb{Q} \mid \forall c \in \mathcal{X}^\#, \rho \models c \}$$

- $\gamma(\mathcal{X}^\#)$  is a **closed convex polyhedron** of  $(\mathcal{V} \rightarrow \mathbb{Q}) \simeq \mathbb{Q}^{|\mathcal{V}|}$
- $\gamma(\mathcal{X}^\#)$  may be empty, bounded, or **unbounded**

# Polyhedra representations



- **No memory bound** on the representations (even minimal ones)
- No best abstraction  $\alpha$
- Dual representation using generators  
(double description method)



# Polyhedra algorithms

## Fourier-Motzkin elimination:

*Fourier*( $\mathcal{X}^\sharp, v_k$ ) eliminates  $v_k$  from all the constraints in  $\mathcal{X}^\sharp$ :

$$\begin{aligned}
 \textit{Fourier}(\mathcal{X}^\sharp, v_k) &\stackrel{\text{def}}{=} \\
 &\{ (\sum_i \alpha_i v_i \geq \beta) \in \mathcal{X}^\sharp \mid \alpha_k = 0 \} \cup \\
 &\{ (-\alpha_k^-)c^+ + \alpha_k^+c^- \mid c^+ = (\sum_i \alpha_i^+ v_i \geq \beta^+) \in \mathcal{X}^\sharp, \alpha_k^+ > 0, \\
 &\quad c^- = (\sum_i \alpha_i^- v_i \geq \beta^-) \in \mathcal{X}^\sharp, \alpha_k^- < 0 \}
 \end{aligned}$$

### Semantics

$$\gamma(\textit{Fourier}(\mathcal{X}^\sharp, v_k)) = \{ \rho[v_k \mapsto v] \mid v \in \mathbb{Q}, \rho \in \gamma(\mathcal{X}^\sharp) \}$$

i.e., forget the value of  $v_k$

# Polyhedra algorithms

## Linear programming:

$$\mathit{simplex}(\mathcal{X}^\#, \vec{\alpha}) \stackrel{\text{def}}{=} \min \{ \sum_i \alpha_i \rho(\mathbf{v}_i) \mid \rho \in \gamma(\mathcal{X}^\#) \}$$

Application: remove **redundant constraints**:

for each  $c = (\sum_i \alpha_i \mathbf{v}_i \geq \beta) \in \mathcal{X}^\#$

if  $\beta \leq \mathit{simplex}(\mathcal{X}^\# \setminus \{c\}, \vec{\alpha})$ , then remove  $c$  from  $\mathcal{X}^\#$

(e.g., *Fourier* causes a quadratic growth in constraint number, most of which are redundant)

Note: calling *simplex* many times can be **costly**

- use fast syntactic checks first
- check against the bounding-box first
- use *simplex* as a last resort

# Polyhedra abstract operators

**Order:**  $\subseteq^\#$

$$\mathcal{X}^\# \subseteq^\# \mathcal{Y}^\# \stackrel{\text{def}}{\iff} \forall (\sum_i \alpha_i \mathbf{v}_i \geq \beta) \in \mathcal{Y}^\#, \text{simplex}(\mathcal{X}^\#, \vec{\alpha}) \geq \beta$$

$$\stackrel{\text{def}}{\iff} \gamma(\mathcal{X}^\#) \subseteq \gamma(\mathcal{Y}^\#)$$

$$\mathcal{X}^\# =^\# \mathcal{Y}^\# \stackrel{\text{def}}{\iff} \mathcal{X}^\# \subseteq^\# \mathcal{Y}^\# \wedge \mathcal{Y}^\# \subseteq^\# \mathcal{X}^\#$$

# Polyhedra abstract operators (cont.)

## Convex hull:

- Express a point  $\vec{V} \in \mathcal{X}^\# \cup \mathcal{Y}^\#$  as a **convex combination**:  
 $\vec{V} = \sigma \vec{X} + \sigma' \vec{Y}$  for  $\vec{X} \in \mathcal{X}^\#, \vec{Y} \in \mathcal{Y}^\#, \sigma + \sigma' = 1, \sigma, \sigma' \geq 0$
- as  $\sigma \vec{X} + \sigma' \vec{Y}$  is **quadratic**  
 we consider instead:  $\vec{V} = \vec{X} + \vec{Y}$  with  $\vec{X}/\sigma \in \mathcal{X}^\#, \vec{Y}/\sigma' \in \mathcal{Y}^\#$   
 i.e.,  $\vec{X} \in \sigma \mathcal{X}^\#, \vec{Y} \in \sigma' \mathcal{Y}^\#$   
 (adds closure points on unbounded polyhedra)

Formally:

$$\mathcal{X}^\# \cup \mathcal{Y}^\# \stackrel{\text{def}}{=} \text{Fourier}(\dots)$$

$$\text{Fourier}(\{ (\sum_j \alpha_j \mathbf{X}_j - \beta \sigma \geq 0) \mid (\sum_j \alpha_j \mathbf{V}_j \geq \beta) \in \mathcal{X}^\# \} \cup \{ (\sum_j \alpha_j \mathbf{Y}_j - \beta \sigma' \geq 0) \mid (\sum_j \alpha_j \mathbf{V}_j \geq \beta) \in \mathcal{Y}^\# \} \cup \{ \mathbf{V}_j = \mathbf{X}_j + \mathbf{Y}_j \mid \mathbf{V}_j \in \mathcal{V} \} \cup \{ \sigma \geq 0, \sigma' \geq 0, \sigma + \sigma' = 1 \}, \{ \mathbf{X}_j, \mathbf{Y}_j \mid \mathbf{V}_j \in \mathcal{V} \} \cup \{ \sigma, \sigma' \} )$$

[Benoi et al. 96]

# Polyhedra abstract operators (cont.)

**Precise abstract commands:** (exact)

$$C^\sharp[\sum_i \alpha_i \mathbf{v}_i + \beta \leq 0] \mathcal{X}^\sharp \stackrel{\text{def}}{=} \mathcal{X}^\sharp \cup \{(\sum_i \alpha_i \mathbf{v}_i + \beta \leq 0)\}$$

$$C^\sharp[\mathbf{v}_j := [-\infty, +\infty]] \mathcal{X}^\sharp \stackrel{\text{def}}{=} \text{Fourier}(\mathcal{X}^\sharp, \mathbf{v}_j)$$

$$C^\sharp[\mathbf{v}_j := \sum_i \alpha_i \mathbf{v}_i + \beta^\sharp] \mathcal{X}^\sharp \stackrel{\text{def}}{=} \\ \text{subst}(\mathbf{v} \mapsto \mathbf{v}_i, \text{Fourier}((\mathcal{X}^\sharp \cup \{\mathbf{v} = \sum_i \alpha_i \mathbf{v}_i + \beta\}), \mathbf{v}_j))$$

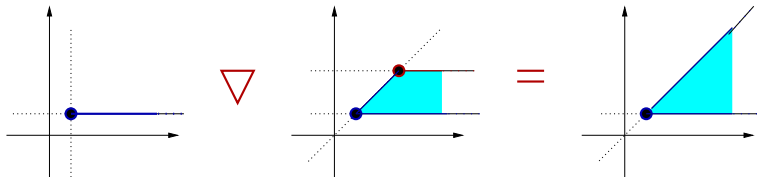
# Polyhedra widening

**Classic widening**  $\nabla$  in  $\mathcal{D}^\#$

$$\mathcal{X}^\# \nabla \mathcal{Y}^\# \stackrel{\text{def}}{=} \{ c \in \mathcal{X}^\# \mid \mathcal{Y}^\# \subseteq^\# \{c\} \}$$

- suppress unstable constraints

**Example:**



# Floating-point domains

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# Floating-point uses

Two **independent** problems:

- **Implement the analyzer using floating-point**

goal: trade precision for efficiency

exact rational arithmetic can be costly  
coefficients can grow large (polyhedra)

- **Analyze floating-point programs**

goal: catch run-time errors caused by rounding  
(overflow, division by 0, ...)

Also: a floating-point analyzer for floating-point programs.

Challenge: how to stay **sound**?



# Floating-point expressions

## Floating-point expressions $\text{exp}_f$

$\text{exp}_f$	::=	$[c, c']$	constant range $c, c' \in \mathbb{F}, c \leq c'$
		$V$	variable $V \in \mathcal{V}$
		$\ominus \text{exp}_f$	negation
		$\text{exp}_f \odot_r \text{exp}_f$	operator $\odot \in \{\oplus, \ominus, \otimes, \oslash\}$

(we use circled operators to distinguish them from operators in  $\mathbb{Q}$ )

## Concrete semantics of expressions

**Semantics of rounding:**  $R_r: \mathbb{Q} \rightarrow \mathbb{F} \cup \{\mathcal{O}\}$ .

Example definition:

$$R_{+\infty}(x) \stackrel{\text{def}}{=} \begin{cases} \min \{ y \in \mathbb{F} \mid y \geq x \} & \text{if } x \leq Mf \\ \mathcal{O} & \text{if } x > Mf \end{cases}$$

$$R_{-\infty}(x) \stackrel{\text{def}}{=} \begin{cases} \max \{ y \in \mathbb{F} \mid y \leq x \} & \text{if } x \geq -Mf \\ \mathcal{O} & \text{if } x < -Mf \end{cases}$$

Notes:

- $\forall x, r, R_{-\infty}(x) \leq R_r(x) \leq R_{+\infty}(x)$
- $\forall r, R_r$  is **monotonic**

## Concrete semantics of expressions (cont.)

$\underline{E[e_f]} : (\mathcal{V} \rightarrow \mathbb{F}) \rightarrow \mathcal{P}(\mathbb{F} \cup \{\mathcal{O}\})$  (expression semantics)

$$E[\mathbf{v}] \rho \stackrel{\text{def}}{=} \{ \rho(\mathbf{v}) \}$$

$$E[\mathbf{[c, c']}] \rho \stackrel{\text{def}}{=} \{ x \in \mathbb{F} \mid c \leq x \leq c' \}$$

$$E[\ominus e_f] \rho \stackrel{\text{def}}{=} \{ -x \mid x \in E[e_f] \rho \cap \mathbb{F} \} \cup (\{ \mathcal{O} \} \cap E[e_f] \rho)$$

$$E[e_f \odot_r e'_f] \rho \stackrel{\text{def}}{=} \\ \{ R_r(x \cdot y) \mid x \in E[e_f] \rho \cap \mathbb{F}, y \in E[e'_f] \rho \cap \mathbb{F} \} \cup \\ \{ \mathcal{O} \mid \text{if } \mathcal{O} \in E[e_f] \rho \cup E[e'_f] \rho \} \\ \{ \mathcal{O} \mid \text{if } 0 \in E[e'_f] \rho \text{ and } \odot = \emptyset \}$$

$\underline{C[c]} : \mathcal{P}(\mathcal{V} \rightarrow \mathbb{F}) \rightarrow \mathcal{P}((\mathcal{V} \rightarrow \mathbb{F}) \cup \{\mathcal{O}\})$  (command semantics)

$$C[\mathbf{X := e_f}] \mathcal{X} \stackrel{\text{def}}{=} \{ \rho[\mathbf{X} \mapsto v] \mid \rho \in \mathcal{X}, v \in E[e_f] \rho \cap \mathbb{F} \} \\ \cup (\{ \mathcal{O} \} \cap E[e_f] \mathcal{X})$$

$$C[e_f \leq 0] \mathcal{X} \stackrel{\text{def}}{=} \{ \rho \mid \rho \in \mathcal{X}, \exists v \in E[e_f] \rho \cap \mathbb{F}, v \leq 0 \} \\ \cup (\{ \mathcal{O} \} \cap E[e_f] \mathcal{X})$$

# Floating-point interval domain

Representation:  $\mathcal{B}^\# \stackrel{\text{def}}{=} \{ [a, b] \mid a \in \mathbb{F}, b \in \mathbb{F}, a \leq b \}$

Expression semantics:  $E^\# \llbracket \text{exp}_f \rrbracket : (\mathcal{V} \rightarrow \mathcal{B}^\#) \rightarrow (\mathcal{B}^\# \cup \{ \mathcal{O} \})$

$$\begin{aligned}
 [a, b] \oplus^\# [a', b'] &\stackrel{\text{def}}{=} [R_{-\infty}(a + a'), R_{+\infty}(b + b')] \\
 [a, b] \ominus^\# [a', b'] &\stackrel{\text{def}}{=} [R_{-\infty}(a - b'), R_{+\infty}(b - a')] \\
 [a, b] \otimes^\# [a', b'] &\stackrel{\text{def}}{=} [R_{-\infty}(\min(aa', ab', ba', bb')), \\
 &\quad R_{+\infty}(\max(aa', ab', ba', bb'))]
 \end{aligned}$$

- We suppose  $r$  is unknown and assume a worst case rounding.
- Soundness stems from the monotonicity of  $R_{-\infty}$  and  $R_{+\infty}$ .
- Abstract operators also use float arithmetic (efficiency).

# Expression linearization

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# Floating-point issues in relational domains

Relational domains assume many powerful **properties** on  $\mathbb{Q}$ :  
 associativity, distributivity, . . . that are **not true on  $\mathbb{F}$** !

**Example:** Fourier-Motzkin elimination

$$X - Y \leq c \quad \wedge \quad Y - Z \leq d \quad \implies \quad X - Z \leq c + d$$

$$X \ominus_n Y \leq c \quad \wedge \quad Y \ominus_n Z \leq d \quad \not\implies \quad X \ominus_n Z \leq c \oplus_n d$$

$$(X = 1, Y = 10^{38}, Z = -1, c = X \ominus_n Y = -10^{38}, \\ d = Y \ominus_n Z = 10^{38}, c \oplus_n d = 0, X \ominus_n Z = 2 > 0)$$

We cannot manipulate float expressions as easily as rational ones!

**Solution:**

keep representing and manipulating rational expressions

- abstract **float** expressions from programs into **rational** ones
- feed them to a **rational** abstract domain
- (optional) **implement** the **rational** domain using **floats**

# Affine interval forms

We put expressions in **affine interval form**: [Miné 04]

$$\text{exp}_\ell ::= [a_0, b_0] + \sum_k [a_k, b_k] \times \mathbf{v}_k$$

## Semantics:

$$\mathbb{E}[\![ e_\ell ]\!] \rho \stackrel{\text{def}}{=} \{ c_0 + \sum_k c_k \times \rho(\mathbf{v}_k) \mid \forall i, c_i \in [a_i, b_i] \}$$

(evaluated in  $\mathbb{Q}$ )

## Advantages:

- **affine** expressions are easy to manipulate
- **interval coefficients** allow non-determinism in expressions, hence, the opportunity for **abstraction**
- **intervals** can easily model **rounding errors**
- easy to design algorithms for  $C^\sharp[\![ X := e_\ell ]\!]$  and  $C^\sharp[\![ e_\ell \leq 0 ]\!]$  in most domains

# Affine interval form algebra

## Operations on affine interval forms:

- adding  $\boxplus$  and subtracting  $\boxminus$  two forms
- multiplying  $\boxtimes$  and dividing  $\boxdiv$  a form by an interval

Using interval arithmetic  $\oplus^\sharp$ ,  $\ominus^\sharp$ ,  $\otimes^\sharp$ ,  $\oslash^\sharp$ :

$$(i_0 + \sum_k i_k \times v_k) \boxplus (i'_0 + \sum_k i'_k \times v_k) \stackrel{\text{def}}{=} (i_0 \oplus^\sharp i'_0) + \sum_k (i_k \oplus^\sharp i'_k) \times v_k$$

$$i \boxtimes (i_0 + \sum_k i_k \times v_k) \stackrel{\text{def}}{=} (i \otimes^\sharp i_0) + \sum_k (i \otimes^\sharp i_k) \times v_k$$

...

**Intervalization:**  $\iota : (\text{exp}_\ell \times \mathcal{D}^\sharp) \rightarrow \text{exp}_\ell$

Intervalization flattens the expression into a single interval:

$$\iota(i_0 + \sum_k i_k \times v_k, \mathcal{X}^\sharp) \stackrel{\text{def}}{=} i_0 \oplus^\sharp \sum_k^\sharp (i_k \otimes^\sharp \pi_k(\mathcal{X}^\sharp)).$$



# Linearization of rational expressions

Linearization without rounding errors:  $\ell : (\text{exp} \times \mathcal{D}^\#) \rightarrow \text{exp}_\ell$

Defined by induction on the syntax of expressions:

- $\ell(v, \mathcal{X}^\#) \stackrel{\text{def}}{=} [1, 1] \times v$
- $\ell([a, b], \mathcal{X}^\#) \stackrel{\text{def}}{=} [a, b]$
- $\ell(e_1 + e_2, \mathcal{X}^\#) \stackrel{\text{def}}{=} \ell(e_1, \mathcal{X}^\#) \boxplus \ell(e_2, \mathcal{X}^\#)$
- $\ell(e_1 - e_2, \mathcal{X}^\#) \stackrel{\text{def}}{=} \ell(e_1, \mathcal{X}^\#) \boxminus \ell(e_2, \mathcal{X}^\#)$
- $\ell(e_1 / e_2, \mathcal{X}^\#) \stackrel{\text{def}}{=} \ell(e_1, \mathcal{X}^\#) \boxtimes \iota(\ell(e_2, \mathcal{X}^\#), \mathcal{X}^\#)$
- $\ell(e_1 \times e_2, \mathcal{X}^\#) \stackrel{\text{def}}{=} \text{can be } \begin{cases} \text{either} & \iota(\ell(e_1, \mathcal{X}^\#), \mathcal{X}^\#) \boxtimes \ell(e_2, \mathcal{X}^\#) \\ \text{or} & \iota(\ell(e_2, \mathcal{X}^\#), \mathcal{X}^\#) \boxtimes \ell(e_1, \mathcal{X}^\#) \end{cases}$

# Linearization of floating-point expressions

## Rounding an affine interval form: (32-bit single precision)

- if the result is normalized: we have a **relative error**  $\varepsilon$  with magnitude  $2^{-23}$ :

$$\varepsilon([a_0, b_0] + \sum_k [a_k, b_k] \times v_k) \stackrel{\text{def}}{=} \max(|a_0|, |b_0|) \times [-2^{-23}, 2^{-23}] + \sum_k (\max(|a_k|, |b_k|) \times [-2^{-23}, 2^{-23}] \times v_k)$$

- if the result is denormalized, we have an **absolute error**  $\omega \stackrel{\text{def}}{=} [-2^{-149}, 2^{-149}]$ .

⇒ we sum these two sources of rounding errors

## Linearization with rounding errors: $\ell : (\text{exp}_f \times \mathcal{D}^\#) \rightarrow \text{exp}_\ell$

$$\ell(e_1 \oplus_r e_2, \mathcal{X}^\#) \stackrel{\text{def}}{=} \ell(e_1, \mathcal{X}^\#) \boxplus \ell(e_2, \mathcal{X}^\#) \boxplus \varepsilon(\ell(e_1, \mathcal{X}^\#)) \boxplus \varepsilon(\ell(e_2, \mathcal{X}^\#)) \boxplus \omega$$

$$\ell(e_1 \otimes_r e_2, \mathcal{X}^\#) \stackrel{\text{def}}{=} \iota(\ell(e_1, \mathcal{X}^\#), \mathcal{X}^\#) \boxtimes (\ell(e_2, \mathcal{X}^\#) \boxplus \varepsilon(\ell(e_2, \mathcal{X}^\#))) \boxplus \omega$$

...

# Applications of the floating-point linearization

## Soundness of the linearization

$\forall e, \forall \mathcal{X}^\# \in \mathcal{D}^\#, \forall \rho \in \gamma(\mathcal{X}^\#),$

if  $\mathcal{O} \notin E[e] \rho$ , then  $E[e] \rho \subseteq E[\ell(e, \mathcal{X}^\#)] \rho$

Application:  $C^\#[V := e] \mathcal{X}^\#$

- check that  $\mathcal{O} \notin E[e] \rho$  for  $\rho \in \gamma(\mathcal{X}^\#)$  with interval arithmetic
- compute  $C^\#[V := e] \mathcal{X}^\#$  as  $C^\#[V := \ell(e, \mathcal{X}^\#)] \mathcal{X}^\#$
- (use  $C^\#[V := [-Mf, Mf]] \mathcal{X}^\#$  if  $\mathcal{O} \in E[e] \rho$ )

## Application : the Astrée analyzer

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# The Astrée static analyzer

## **Analyseur statique de programmes temps-réels embarqués** (static analyzer for real-time embedded software)

- developed at **ENS** (since 2001)
  - | B. Blanchet, P. Cousot, R. Cousot, J. Feret,  
| L. Mauborgne, D. Monniaux, A. Miné, X. Rival
- industrialized and made commercially available by **AbsInt**  
(since 2009)



Astrée

[www.astree.ens.fr](http://www.astree.ens.fr)



AbsInt

[www.absint.com](http://www.absint.com)

[Blanchet et al. 03]

# Specialized static analyzers

## Design by refinement:

- **focus** on a specific family of programs and properties
- start with a fast and **coarse** analyzer (intervals)
- while the precision is insufficient (too many false alarms)
  - add **new abstract domains** (generic or application-specific)
  - **refine** existing domains (better transfer functions)
  - **improve** communication between domains (reductions)

⇒ analyzer **specialized** for a (infinite) class of programs

- efficient and precise
- parametric (by end-users, to analyze new programs in the family)
- extensible (by developers, to analyze related families)

# Astrée applications



Airbus A340-300 (2003)



Airbus A380 (2004)



(model of) ESA ATV (2008)

- size: from 70 000 to 860 000 lines of C
- analysis time: from 45mn to  $\simeq$ 40h
- alarm(s): 0 (proof of absence of run-time error)

# Sound floating-point polyhedra

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# Sound floating-point polyhedra

Algorithms to adapt: [Chen al. 08]

- **linear programming:**

$$\mathit{simplex}_f(\mathcal{X}^\#, \vec{\alpha}) \leq \mathit{simplex}(\mathcal{X}^\#, \vec{\alpha})$$

$$\mathit{simplex}(\mathcal{X}^\#, \vec{\alpha}) \stackrel{\text{def}}{=} \min \{ \sum_k \alpha_k \rho(\mathbf{v}_k) \mid \rho \in \gamma(\mathcal{X}^\#) \}$$

- **Fourier-Motzkin elimination:**

$$\mathit{Fourier}_f(\mathcal{X}^\#, \mathbf{v}_k) \Leftarrow \mathit{Fourier}(\mathcal{X}^\#, \mathbf{v}_k)$$

$$\begin{aligned} \mathit{Fourier}(\mathcal{X}^\#, \mathbf{v}_k) &\stackrel{\text{def}}{=} \\ &\{ (\sum_i \alpha_i \mathbf{v}_i \geq \beta) \in \mathcal{X}^\# \mid \alpha_k = 0 \} \cup \\ &\{ (-\alpha_k^-)c^+ + \alpha_k^+c^- \mid c^+ = (\sum_i \alpha_i^+ \mathbf{v}_i \geq \beta^+) \in \mathcal{X}^\#, \alpha_k^+ > 0, \\ &\quad c^- = (\sum_i \alpha_i^- \mathbf{v}_i \geq \beta^-) \in \mathcal{X}^\#, \alpha_k^- < 0 \} \end{aligned}$$

# Sound floating-point linear programming

## Guaranteed linear programming: [Neumaier Shcherbina 04]

Goal: **under-approximate**  $\mu = \min \{ \vec{c} \cdot \vec{x} \mid \mathbf{M} \times \vec{x} \leq \vec{b} \}$

knowing that  $\vec{x} \in [\vec{x}_l, \vec{x}_h]$  (bounding-box for  $\gamma(\mathcal{X}^\sharp)$ ).

- compute any approximation  $\tilde{\mu}$  of the **dual problem**:

$$\tilde{\mu} \simeq \mu = \max \{ \vec{b} \cdot \vec{y} \mid {}^t\mathbf{M} \times \vec{y} = \vec{c}, \vec{y} \leq \vec{0} \}$$

and the corresponding vector  $\vec{y}$

(e.g. using an off-the-shelf solver;  $\tilde{\mu}$  may over-approximate or under-approximate  $\mu$ )

- compute with intervals safe bounds  $[\vec{r}_l, \vec{r}_h]$  for  $\mathbf{A} \times \vec{y} - \vec{c}$ :

$$[\vec{r}_l, \vec{r}_h] = ({}^t\mathbf{A} \otimes^\sharp \vec{y}) \ominus^\sharp \vec{c}$$

and then:

$$\nu = \inf((\vec{b} \otimes^\sharp \vec{y}) \ominus^\sharp ([\vec{r}_l, \vec{r}_h] \otimes^\sharp [\vec{x}_l, \vec{x}_h]))$$

then:  $\nu \leq \mu$ .

# Sound floating-point Fourier-Motzkin elimination

Given:

- $c^+ = (\sum_i \alpha_i^+ v_i \geq \beta^+)$  with  $\alpha_k^+ > 0$
- $c^- = (\sum_i \alpha_i^- v_i \geq \beta^-)$  with  $\alpha_k^- < 0$
- a bounding-box of  $\gamma(\mathcal{X}^\#)$ :  $[\vec{x}_l, \vec{x}_h]$

We wish to compute  $\sum_{i \neq k} \alpha_i v_i \geq \beta$  in  $\mathbb{F}$   
 implied by  $(-\alpha_k^-)c^+ + \alpha_k^+c^-$  in  $\gamma(\mathcal{X}^\#)$ .

- **normalize**  $c^+$  and  $c^-$  using interval arithmetic:

$$\begin{cases} v_k + \sum_{i \neq k} (\alpha_i^+ \otimes^\# \alpha_k^+) v_i \geq \beta^+ \otimes^\# \alpha_k^+ \\ -v_k + \sum_{i \neq k} (\alpha_i^- \otimes^\# (-\alpha_k^-)) v_i \geq \beta^- \otimes^\# (-\alpha_k^-) \end{cases}$$

(interval affine forms)

- **add** them using interval arithmetic:

$$\sum_{i \neq k} [a_i, b_i] v_i \geq [a_0, b_0]$$

where  $[a_i, b_i] = (\alpha_i^+ \otimes^\# \alpha_k^+) \ominus^\# (\alpha_i^- \otimes^\# \alpha_k^-)$ ,

$[a_0, b_0] = (\beta^+ \otimes^\# \alpha_k^+) \ominus^\# (\beta^- \otimes^\# \alpha_k^-)$ .

# Sound floating-point Fourier-Motzkin elimination (cont.)

- **linearize** the interval affine form  $\sum_{i \neq k} [a_i, b_i] \mathbf{v}_i \geq [a_0, b_0]$  into an affine form  $\sum_{i \neq k} \alpha_i \mathbf{v}_i \geq \beta$

we choose:

- $\alpha_i \in [a_i, b_i]$
- $\beta = \sup ([a_0, b_0] \oplus^\# \bigoplus_{i \neq k}^\# (|\alpha_i \ominus^\# [a_i, b_i]|) \otimes^\# |[\vec{x}_l, \vec{x}_h]|)$

## Soundness:

For all choices of  $\alpha_i \in [a_i, b_i]$ ,  
 $\sum_{i \neq k} \alpha_i \mathbf{v}_k \geq \beta$  holds in  $\text{Fourier}(\mathcal{X}^\#, \mathbf{v}_k)$ .  
 (e.g.  $\alpha_i = (a_i \oplus_n b_i) \oslash 2$ )

# Consequences of rounding

## Precision loss:

- Projection:

$$\begin{aligned} \gamma(\text{Fourier}_f(\mathcal{X}^\#, \mathbf{V}_k)) &\supseteq \{ \rho[\mathbf{V}_k \mapsto v] \mid v \in \mathbb{Q}, \rho \in \gamma(\mathcal{X}^\#) \} \\ &= \\ &\text{C}[\mathbf{V}_k := [-\infty, +\infty]] \gamma(\mathcal{X}^\#) \end{aligned}$$

- Order:

$$\mathcal{X}^\# \subseteq^\# \mathcal{Y}^\# \implies \gamma(\mathcal{X}^\#) \subseteq \gamma(\mathcal{Y}^\#) \quad (\neq)$$

- Join:

$$\gamma(\mathcal{X}^\# \cup^\# \mathcal{Y}^\#) \supseteq \text{ConvexHull}(\gamma(\mathcal{X}^\#) \cup \gamma(\mathcal{Y}^\#)) \quad (\neq)$$

## Efficiency loss:

- cannot remove all redundant constraints

# Abstraction summary

## Floating-point polyhedra analyzer for floating-point programs

### expression abstraction

float expression  $e_f$

↓ linearization

affine form  $e_\ell$  in  $\mathbb{Q}$

↓ float implementation

affine form  $e_\ell$  in  $\mathbb{F}$

### environment abstraction

$\mathcal{P}(\mathcal{V} \rightarrow \mathbb{F})$

↓ abstract domain

polyhedra in  $\mathbb{Q}$

↓ float implementation

polyhedra in  $\mathbb{F}$

↓ widening

polyhedra in  $\mathbb{F}$

→

**The end**

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